Detecting Urban Clues for Road Safety
Leveraging Big Data and Machine Learning
DECEMBER 2021
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The Global Program for Resilient Housing supports safe and resilient housing by creating new, cost-saving tools to evaluate homes from the air and the street to help identify those vulnerable to natural and health hazards. While the program focuses on housing, it developed a methodology to extract urban clues from street view imagery with multiple applications including those related to urban mobility and road safety.

The note incorporates valuable input and review from Holly Krambeck (Program Manager), Said Dahdah (Lead Transport Specialist), Satoshi Ogita (Senior Transport Specialist), Veronica Ines Raffo (Senior Infrastructure Specialist), Li Qu (Senior Transport Specialist), and Glenn S. Morgan (ESF Consultant).

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Objective, Audience and Structure

The purpose of this Guidance Note is to provide concrete guidance on how big data and machine learning (ML) can be leveraged in road safety analysis. The document presents opportunities to use these new technologies to improve current methods for data collection and analysis for various road safety assessments.

This Guidance Note provides a practical guide for using new data sources and analytical methods for road safety analysis in different types of projects that may impact road infrastructure or risk-related factors. Road safety practitioners, project managers, researchers, international development organizations, data scientists, and government agencies responsible for road safety assessments, transportation management, and infrastructure development would also find this document useful to understand how these new technologies can be implemented for various road safety assessment procedures and requirements.

This document consists of three parts. Part 1 provides an overview of existing approaches and tools for road safety assessment and identifies opportunities to improve these using new technologies such as big data and ML. Part 2 provides an overview of these new technologies and concrete guidance on how they can be integrated into transport projects for road safety analysis. Part 3 presents case studies on two regions of interest – Bogotá, Colombia and Padang, Indonesia – to demonstrate how ML can be implemented to evaluate road safety. The document concludes with recommendations for using big data and ML in road safety assessments in the future.
# Abbreviations

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
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<tbody>
<tr>
<td>ADB</td>
<td>Asian Development Bank</td>
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<tr>
<td>API</td>
<td>Application Programming Interface</td>
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<td>DDP</td>
<td>Development Data Partnership</td>
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<td>DL</td>
<td>Deep Learning</td>
</tr>
<tr>
<td>DRIVER</td>
<td>Data for Road Incident Visualization, Evaluation and Reporting</td>
</tr>
<tr>
<td>FSI</td>
<td>Fatalities and Serious Injuries</td>
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<td>GRSF</td>
<td>Global Road Safety Facility (World Bank)</td>
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<tr>
<td>IoT</td>
<td>Internet of Things</td>
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<tr>
<td>iRAP</td>
<td>International Road Assessment Programme</td>
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<tr>
<td>ITS</td>
<td>Intelligent Transport System</td>
</tr>
<tr>
<td>LMICs</td>
<td>Low- and Middle-Income Countries</td>
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<tr>
<td>ML</td>
<td>Machine Learning</td>
</tr>
<tr>
<td>OSM</td>
<td>OpenStreetMap</td>
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<tr>
<td>RIC</td>
<td>Road Information Collector</td>
</tr>
<tr>
<td>ROI</td>
<td>Region of Interest</td>
</tr>
<tr>
<td>RRE</td>
<td>Road Risk Evaluator</td>
</tr>
<tr>
<td>RSA</td>
<td>Road Safety Audit</td>
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<tr>
<td>RSI</td>
<td>Road Safety Inspection</td>
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<td>RSIA</td>
<td>Road Safety Impact Assessment</td>
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<tr>
<td>RSO</td>
<td>Road Safety Observatory</td>
</tr>
<tr>
<td>SDGs</td>
<td>Sustainable Development Goals</td>
</tr>
<tr>
<td>UAV</td>
<td>Unmanned Aerial Vehicle</td>
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Introduction

Transportation services and infrastructure connect people, businesses, and places. They allow citizens to access opportunities, such as jobs, education, health services, recreation, and enable the movement and distribution of goods. As a result, transport services and infrastructure are key to the economic development of cities and regions.\(^1\)

While the development of transportation systems and infrastructure is vital to economic growth, it is also important to evaluate and mitigate its potential negative externalities and costs to society.\(^2\) According to the World Health Organization (WHO), around 1.25 million people are killed on the world’s roads every year and between 20 and 50 million are seriously injured. These costs are disproportionately higher in low- and middle-income countries (LMICs), which are estimated to endure 93 percent of the world’s fatalities on the road, despite having 60 percent of the world’s vehicles (figure 1).\(^3\) According to a 2019 study of select countries, road crashes cost World Bank client countries an estimated 7 percent to 22 percent of their GDP over a 24-year period.\(^4\)

Road fatalities and injuries are predictable and preventable.\(^5\) Research indicates that roughly 70 percent of serious crashes are due to simple and unintentional errors of perception or judgement.\(^6\) The most vulnerable road users are pedestrians, bicyclists, and motorcyclists, accounting for more than 50 percent of reported fatalities in LMICs.\(^7\) Effective transport planning and management that carefully considers and incorporates measures to address safety risks.\(^8\) Speed reductions and the design of infrastructure to promote safer streets have demonstrated clear results in Colombia and India. In Bogotá, Colombia, the speed management program resulted in a 21 percent decrease in traffic fatalities compared to the average for the three preceding years (2015-18).\(^9\) In India, Pune has become a regional leader in complete streets, in which streets are designed for all users, rather than only for cars; pedestrians, cyclists, motorists, and transit riders are given safe access with the complete streets approach.\(^10\)

The United Nations (UN) launched its second Decade of Action for Road Safety in 2020 to address the road safety objectives of its Sustainable Development Goals (SDGs). These include SDG 3.6, which seeks to reduce deaths and injuries from road crashes by 50 percent, and SDG 11, which focuses on making cities and human settlements inclusive, safe, resilient, and sustainable.

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9 International Transport Forum, “Best Practice for Urban Road Safety: Case Studies.”
The World Bank hosts the Global Road Safety Facility (GRSF) to provide funding, knowledge, and technical assistance to help developing countries create safer roads. The Facility addresses road safety issues across a wide range of projects, from infrastructure design and vehicle safety to traffic law enforcement, post-crash response systems, data collection, and institutional strengthening. Since its inception in 2006, the Facility has disbursed a total of USD 44.6 million to improve road safety in 64 countries.

It is important, and often required, to incorporate road safety management procedures in transport projects to identify and mitigate risks in a timely manner. Governments, international development organizations, and other agencies have established various tools and systems to facilitate road safety analysis. However, the absence of valid, representative data presents significant challenges to developing a good understanding of road safety risks and reducing crash fatalities and injuries through data-driven, evidence-based interventions.11

New technologies such as big data and machine learning (ML) provide promising opportunities to improve existing data sources and methods for road safety analysis. From analyzing anonymized GPS data to understand traffic flows in the Philippines to part-

nering with data providers that crowdsource information about crash sites in Kenya, governments, road safety practitioners, and other stakeholders are adopting innovative approaches to identify, monitor, and mitigate fatalities and injuries in high-risk areas. Unsupervised learning techniques have been applied in Lima, Peru, using records of different crash types to identify safe areas along routes and safer pedestrian pathways, decreasing the likelihood of pedestrians suffering an accident. The Urban Traffic Modeling and Control project at the National University of Medellín has been using deep learning (DL) techniques to classify traffic and identify motorbike usage. In Cartagena, Colombia, data mining and ML algorithms were used to analyze road records and predict the severity of crashes using classification algorithms. Figure 2 provides an overview of the potential uses of big data and ML in road safety analysis that will be discussed in this note.

FIGURE 2: Potential applications of big data and ML in road safety projects

<table>
<thead>
<tr>
<th>BIG DATA OR SPATIAL DATA SOURCE</th>
<th>MACHINE/DEEP LEARNING</th>
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<tbody>
<tr>
<td>Street view imagery</td>
<td>Identify road conditions, barriers, crosswalks, pedestrian paths, street signs, traffic lights</td>
</tr>
<tr>
<td>Satellite and aerial imagery</td>
<td>Delineate road curvature, complex intersections, road gradient; provide car and truck count</td>
</tr>
<tr>
<td>Internet of Things</td>
<td>Analyze vehicle and population movement</td>
</tr>
<tr>
<td>Incident reports</td>
<td>Identify road crash patterns and develop prediction models</td>
</tr>
<tr>
<td>Natural phenomena</td>
<td>Find patterns in weather and time of day</td>
</tr>
<tr>
<td>Social media</td>
<td>Extract traffic or road condition data</td>
</tr>
</tbody>
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SOURCE: Original figure for this publication.

PART 1:
The Demand for Data to Assess Risks and Conduct Safety Assessments

Road safety practitioners utilize a variety of data-driven tools and methods to evaluate road safety risks and determine mitigation measures across different stages of road and infrastructure development projects. Comprehensive road safety evaluation tools and procedures require both crash and non-crash data to identify issues and measure their associated risks. The variety, quantity, and quality of data available is an important determinant of the tool for measurement and analysis of various road safety indicators.

This section provides an overview of the most widely used road safety assessment tools and their data requirements. A brief description of these road safety assessment procedures and tools can be found in table 1. This brief review of existing approaches informs the suggestions for improving data collection and analysis for road safety evaluation procedures through big data and machine learning (ML).

1.1 Conventional Tools for Road Safety Assessment

Road safety risks arise from the interaction of many different elements. The road and roadside design and engineering, travel speeds, the extent and type of road use, road user behavior, vehicle safety features (both active and passive), and post-crash response. The Safe System approach addresses all of these interactive elements in an integrated manner and emphasizes sharing accountability with designers and users of the road network to achieve road safety targets.15

The primary purpose of road safety assessment procedures is to identify risks in existing or planned infrastructure developments. Road safety practitioners utilize a wide range of tools for this purpose. Some of these can be purchased commercially, while others are provided, and occasionally mandated by local governments. Organizations providing financial support for international development projects may also create their own tools for road safety analysis, such as the “Simplified Methodology” by the World Bank.16 In general, road safety assessment tools tend to comprise checklists for evaluating the safety of road networks at different stages of a road project’s lifecycle. Some tools, such as the Austroads Road Safety Audit tool, provide guidelines for conducting road safety audits at all the stages of a road project, while other tools like iRAP have guidelines for only some stages (such as during preparation and post-construction). Tools may also need to be adapted or customized depending on the type of project or the project location.

A comprehensive approach to managing road safety and reducing crash risk generally requires a combination of reactive and proactive approaches across some or all stages of a road’s lifecycle.17 Reactive approaches rely on historical crash data to identify high risk regions and risk factors. Proactive approaches aim to identify and address potential risks before a project is implemented or crashes occur.

Reactive approaches are often the starting point for road safety analysis and rely on some form of crash-based identification. Crash data-based risk assessments may involve evaluating one or several of the following criteria: infrastructure, users, speeds, vehicle standards and post-crash trauma care. This approach requires that risk factors be constantly monitored and assessed throughout the project lifecycle.

Recently, the focus has shifted toward using more proactive approaches, with a wide range of tools being developed for this purpose. These are especially useful in the absence of crash data, and often involve surveys of existing roads for road infrastructure risk or assessment of other criteria to obtain subjective estimates of road infrastructure risk. Some common tools for proactive road risk assessments are discussed below.

Road Safety Impact Assessments (RSIA) are designed to estimate the potential effects of planned road or traffic developments, or any other interventions that may significantly affect transport conditions and risks to road users. The procedure is often conducted at the planning stage to assess the possible impacts of different schematic designs before the most appropriate design is audited and selected for implementation.

Road Safety Audits (RSA) are generally used to analyze a road project, or any other type of project which affects road users. An independent, qualified team reports on the project’s crash potential and safety performance to identify safety performance for all kinds of road users. Road safety audits can be conducted at various stages in the project lifecycle including planning, preliminary design, detailed design and pre-opening or post-construction stages. However, it is most cost-effective when it is applied to a road or traffic design before construction to ensure that safety is fully integrated into all elements of the project’s infrastructure, with minimal risk of redesign or physical rework.

Road Safety Inspections (RSI) involve a systematic evaluation of an existing road or section of road by a team of seasoned experts. They are conducted on-site to determine potential hazards, faults and deficiencies that could contribute to serious crashes. RSIs are more comprehensive than RSAs and are usually conducted post construction to identify further interventions to improve road safety and inform future projects.

Road Assessment Programmes (RAP) entail a comprehensive review of existing roads and road networks. Most RAPs, such as the EuroRAP, usRAP and iRAP, use a star-rating approach to provide a relative and comparable measure of the safety level of road networks all around the world. RAPs are highly comprehensive, detailed, and costly. They are usually commissioned by national or local governments to evaluate extensive road networks as an ad-hoc project to determine safety interventions and inform further infrastructure development. Therefore, RAPs are either utilized at the preparation stage of a project to determine project scope, design, and other key requirements for pre-appraisal and construction, or they are conducted to assess the impact of major infrastructure development projects during the post-project operations phases.

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18 Phil Allan, “Road Safety Inspections” (presentation, Road Safety Seminar, World Road Association, Lomé, Togo: October 2006). [https://www.piarc.org/ressources/documents/actes-seminaires06/c31-togo06/8718,2-PIARC_Oct06_Allan.pdf](https://www.piarc.org/ressources/documents/actes-seminaires06/c31-togo06/8718,2-PIARC_Oct06_Allan.pdf)
### Data Requirements for Traffic and Road Safety Assessment Tools

One or more types of road safety assessments may be conducted at once or at different phases of a project. Table 2 summarizes the assessment methods, objectives, and their data requirements.

Assessments prepared early in a project’s lifecycle may help to identify and evaluate potential traffic and road safety risks that may arise from the project activities and/or their implementation. Such assessments are intended to help mobilize appropriate resources, analyze risks in detail, and identify and adopt the most appropriate mitigation measures. During the project preparation stage, more in-depth assessments to identify and evaluate potential traffic and road safety risks may need to be conducted. The assessments should consider Safe System principles to ensure that all opportunities to minimize risks have been realized.  

Since the key objectives of these assessments (i.e., identifying risk elements and estimating crash exposure, likelihood, and severity for different road users) are complex and not standardized, the scoring system is subjective. This can complicate comparisons between sites, especially when these have been assessed by different individuals or teams. It is, therefore, usually most suitable for comparing options at a single site, identifying sources of risk and identifying solutions, rather than for comparing different sites.

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19 Tony Bliss and Jeanne Breen, “Meeting the Management Challenges of the Decade of Action for Road Safety.”
**TABLE 2: Overview of data requirements for common road safety assessment tools**

<table>
<thead>
<tr>
<th>METHOD</th>
<th>OBJECTIVES</th>
<th>DATA REQUIREMENTS</th>
</tr>
</thead>
</table>
| Crash data-based risk assessment| Estimate risk using Fatalities and Serious Injuries (FSI) crash data to reflect road infrastructure, users, and speed factors. This is evaluated with vehicle standards and post-crash care. | • Crash data from the previous 3–5 years or estimated from data available from similar roads in the country  
• Assessment of vehicle standards (safe vehicles)  
• Post-crash trauma care (response time, quality of attention) |
| Road Safety Audit (RSA) (performed by an independent team of specialists) | Identify safety concerns. It audits the safety of the specific design of the chosen scheme. | Analysis of project designs and interventions: specialists assess road options, such as intersections, signs, crossings; design standards, and the relationship of this intervention to main network. Main data needed includes:  
• Scheme plans  
• Crash and FSI data  
• Traffic mix and volumes  
• Road features (e.g., design elements, such as bypasses, cycle routes, junction improvements, installation of traffic signals, roundabouts, traffic calming, bend realignment, safety fence schemes and pedestrian crossing facilities) |
| Road Safety Impact Assessment (RSIA) (performed by members of the project design team with road design and road safety auditing experience) | Assess the impact of each of the planning options on the safety performance of the current road network. It estimates the impact of possible schemes on safety for an entire geographic area at the strategic level. | The evaluation of each alternative is based on several factors, some of which include:  
• The scheme objectives  
• Crash and FSI data  
• Traffic mix and volumes  
• Road features  
• Categorization of roads and streets of that network |
| Safe System Assessment (SSA) | Assess how closely road design and operation align with the Safe System objectives, and to clarify which elements need to be modified to achieve closer alignment with these objectives. | The core of this SSA approach is the “Safe System Matrix” framework which is essentially a risk assessment. The assessment is done by scoring the risk exposure, likelihood and severity from 0–4. The Austroads approach can be used to perform this type of assessment. Data needed include:  
• Traffic mix and volumes  
• Road features |

**Key Challenges with Current Approaches to Road Safety Analysis**

Since data is the cornerstone of all road safety assessments, the availability of high quality, reliable data is key to extracting useful, actionable insights and improving road safety conditions. Without quality information, it is difficult to estimate crash locations and crash types, at-risk individuals and groups, and key risk factors influencing exposure to risk, crash involvement, crash severity, and post-crash outcomes. Meeting data requirements for road safety assessments can be a challenge for various reasons, such as the lack of open data, or data collection costs.

There can be a lack of adequate crash data or road ratings in data scarce countries and regions for identifying risk factors. Governments often lack adequate and reliable data to identify road safety risks and perform road safety assessments. In addition, road crashes tend to be underreported, especially in LMICs. There may also be significant gaps in the data in terms of geographic or temporal coverage, or the data may be missing important variables and categories. Access to data can also be limited for certain data types, or the process of obtaining the data may be too complex, costly, and time-consuming.
Collecting data on road safety attributes through manual detection or special equipment can be expensive, time-consuming, and complex.\textsuperscript{20} Budgeting for data collection can be a challenge. In these cases, data is most often estimated through existing road designs or by local transportation agencies. The most cost-effective method for data collection is the installation of cameras and sensors that record street imagery, speed information, and other data. Images and video are then analyzed by road safety experts to identify relevant attributes, assess road conditions, and identify potential risks. Commissioning equipment and hiring resources to manually collect data on road features and design may be a hindrance, especially for smaller-scale projects where the opportunity to benefit from economies of scale is low.

In addition to the quality and availability of data, preparing and analyzing road safety data can also be costly, resource-intensive, and technically demanding. Most road safety assessments require data to be combined from various sources, which often involves aggregating, cleaning and preparing the data. Additional resources and specialist expertise may be necessary for this process, and also to analyze the data and extract useful insights using methods such as clustering and developing spatial models. Conventional statistical techniques can also be limited in their ability to identify complex correlations and underlying factors that may contribute to road safety risks across various projects.

The purpose of this Guidance Note is to identify new methods for the collection and analysis of road safety data that could overcome the limitations of existing approaches, and also improve their efficacy in identifying risks and opportunities to mitigate crashes. Conducting road safety assessments is a required component of most road investment and infrastructure development projects. Advanced technologies such as big data and ML have the potential to not only supplement existing methods, but also significantly reduce costs while improving the efficacy of road safety assessments in identifying risks and opportunities to mitigate crashes.

The following section explains how big data and ML be practically implemented by road safety practitioners for various road safety assessment procedures. It introduces these methods and provides an overview of big data sources and ML techniques that are useful for road safety assessments. Part 2 also discusses best practices and key considerations that are vital to implementing these new methods effectively. A framework for integrating these technologies in road safety assessments is also proposed, and Part 3 demonstrates how this framework can be applied in LMICs through two original case studies.

PART 2: 
Big Data and Machine Learning to Strengthen Road Safety in Transport Projects

Governments, road safety practitioners, international development organizations, and road safety advocates such as the Global Road Safety Facility are keen to use new technologies, such as big data and ML, in data collection and analysis for road safety to overcome the limitations of existing approaches. As these technologies become more sophisticated and accessible, a growing body of research indicates their potential to complement, and eventually even surpass conventional methods.

The usefulness of big data and ML in road safety and other transport and infrastructure projects has been widely demonstrated over the past few years. For example, a World Bank task team developed an open data platform in 2015 based on a pilot in Cebu City, Philippines, which sourced data from a taxi company to generate insights for traffic management.21 Another team has developed a “Simplified Methodology” to implement ML in video analysis to extract data on road attributes. The new tool was piloted across over 500 kilometers of road in Mozambique and Liberia in 2019.22 The World Bank, in collaboration with the Philippines government, has also launched the Data for Road Incident Visualization Evaluation and Reporting (DRIVER) system to facilitate data sharing for road safety analysis. This free web-based, open-source platform connects traffic crash data from multiple agencies through a standardized reporting system. DRIVER also provides tools to geo-spatially analyze road crash data, predict blackspots, estimate the economic costs of crashes, and evaluate the effectiveness of various interventions to support investments and policymaking for improved road safety.23

Road safety practitioners are increasingly turning to data partnerships to obtain crash, traffic, and other types of data for road safety analysis. For example, in Kenya, the WHO estimates that up to 75 percent of crashes go unreported.24 SmarTTrans – a collaboration between the Kenyan government and the World Bank – has worked to fill this gap by bringing together crash information both from administrative records and from bystander crash reports from Twitter.25 In addition, the team has leveraged the Development Data Partnership (DDP) to access Waze API and Uber congestion and speed information for all 6,200 km of the city’s road network. Using all data sources, the smarTTrans team is creating near real-time analytics to facilitate the identification of crash hotspots, speeding, and congestion patterns.

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2.1 New Data (and Big Data) in Road Safety Analysis

Big data is generally understood as extremely large datasets that are generated by a wide range of data sources, including machines, sensors, and other Internet of Things (IoT) devices. Big data can also be captured over the internet through social media and other types of applications, especially those that track locational or transactional data.

The large volume of such data is one of many characteristics that make big data especially useful for road safety and other applications in transport and infrastructure development. For example, big data can be generated at immense velocity, especially as more such data is collected real-time and for large populations. It also occurs in a variety of data formats, from structured databases to unstructured text documents, emails, videos, audios, stock ticker data and financial transactions. Big data is also characterized by a high degree of variability since data flows can change over time, depending on seasons, off-peak hours, or availability of collection methods across an entire population under study. Table 3 provides a SWOT analysis of the use of big data in road safety analysis.

For transport, the increasing use of personal mobile devices and vehicle sensors to collect traffic and location data presents a significant opportunity to augment traditional sources of transport data. Annex 1 discusses the most relevant big data types for road safety analysis. It also provides guidance on the potential applications of these sources for evaluating road safety, and the advantages and disadvantages of each source. The following sections discuss how big data can be used for the various road safety assessment methods and tools discussed in Part 1.
TABLE 3: **SWOT analysis of using big data in road safety analysis**

<table>
<thead>
<tr>
<th>STRENGTHS</th>
<th>WEAKNESSES</th>
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<tbody>
<tr>
<td>• Recent and broad geographic coverage allows researchers to dive deeper into transport issues and get a comprehensive and current picture of risks.</td>
<td>• Requires investment in expertise, software and computing power to store, access and process big data.</td>
</tr>
<tr>
<td>• Can help obtain real-time data and track up-to-the-minute changes in traffic flows and other important variables.</td>
<td>• Availability of data can vary significantly by geography and context.</td>
</tr>
<tr>
<td>• May be faster and easier to obtain and process, compared to manual collection.</td>
<td>• Coverage can be inconsistent or exclude important segments of the population.</td>
</tr>
<tr>
<td>• Can offer higher spatial and temporal resolution than conventional sources.</td>
<td>• Most big data sources are not set up to support road safety assessments—it is often data that was collected for other purposes but gets repurposed for road safety analysis. This can lead to the data being biased, incomplete and/or difficult to incorporate in road safety analysis.</td>
</tr>
<tr>
<td>• Can be more affordable and easier to scale.</td>
<td>• Need to consider the interoperability of different datasets (i.e., how easy it is to combine different datasets for complex road safety assessment models).</td>
</tr>
<tr>
<td>• Vast quantities of data can limit bias from outliers and other sources of &quot;noise&quot; since data gets aggregated across vast populations.</td>
<td>• Changes in privacy laws and other relevant policies can impact quality, consistency and coverage of data.</td>
</tr>
<tr>
<td>• Can help improve data quality since often covers large geographic and/or temporal scope, also allowing for comparison against &quot;control&quot; datasets and scenarios.</td>
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<thead>
<tr>
<th>OPPORTUNITIES</th>
<th>THREATS</th>
</tr>
</thead>
<tbody>
<tr>
<td>• Provides an alternative approach to road safety data collection and analysis that may complement or supplement traditional approaches or datasets. For example, big data sources may be able to collect more accurate crash data.</td>
<td>• Privacy concerns – data should be de-identified and anonymized before use.</td>
</tr>
<tr>
<td>• Big data analysis can uncover new dynamics, complex behavioral patterns and relationships, and correlations that conventional statistical methods and data may not be able to detect.</td>
<td>• Data providers may be reluctant to share data.</td>
</tr>
<tr>
<td>• Growing interest in autonomous vehicles is generating more data about road systems, vehicles, and vulnerable users that can be integrated into road safety analysis.</td>
<td>• Governments, local municipalities, and other stakeholders must invest in technological infrastructure to support big data collection and analysis.</td>
</tr>
<tr>
<td>• Rising momentum for the creation of a &quot;big data platform&quot; where data providers can sell or share data.</td>
<td>• Need to enforce quality control to limit risk of data bias.</td>
</tr>
</tbody>
</table>

Big data, especially when combined with ML, which is discussed in the following section, can **enhance the capabilities of current systems and road safety assessment tools**. The increasing use of IoT devices, which range from smartphones to vehicle sensors, as well as Intelligent Transport Systems (ITS), is making it possible to collect, access and utilize real-time data about a large range of variables that are relevant to road safety analysis. This includes traffic flows, crash sites, peak timings, travel times and road usage by pedestrians, bicyclists, and motorists. The availability of such extensive data creates new possibilities for crash risk modelling, especially to predict the outcomes of various types of road safety interventions as well as possible impacts of road infrastructure projects.

As mobile phone use rises globally, smartphones have become a prominent source of big data, though there are many other sources to consider. In addition to the location and velocity of road travelers collected passively through mobile devices, transportation projects can take advantage of street view, aerial, and satellite imagery, traffic monitoring systems, connected vehicles for road safety analysis, as well as crowdsourced data provided by the community through mobile devices.26 Annex 2 provides an overview of the most relevant and accessible big data sources for road safety analysis. Road safety practitioners are advised to look for relevant local and regional data providers based on the region(s) of interest that concern their project(s). As big data infrastructure advances

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globally and new companies and startups begin data collection for various purposes, it is likely that the list of available big data sources will expand significantly in coming years.

**Street view imagery can complement or potentially substitute manual or commissioned road surveys to collect data on road safety attributes for various types of assessments.** For example, street view imagery can help obtain baseline data for RSIA more quickly and cheaply, especially if the data is not already readily available. By applying ML algorithms to street view images, road attributes and other data can be detected that are important for road safety assessments. Similarly, there may be instances where satellite imagery or aerial imagery, those collected by an unmanned aerial vehicle (UAV) or drone, can be analyzed to detect road or road user attributes. Figure 3 shows the same crosswalk visible in satellite imagery and street view imagery using OpenStreetMap in OSM. ML is discussed in greater detail in the next section.

**FIGURE 3: Street view and OSM**

Road safety data can be extracted from images such as road markings and signs, types of road users, and designated paths for vulnerable users. Each image and relevant attributes are geolocated for further analysis. In this instance, the crosswalk identified in OSM can be verified in street view imagery.

SOURCE: Original figure for this publication derived from OSM, Mapillary, and Maxar Technologies.

**Mobile applications and telematics can provide data related to vehicle movement to identify road infrastructure risks.** This data includes current and historical average speeds along road segments as well as irregularities, like traffic jams and incidents. This data is useful for most proactive road safety assessment tools, including RSIA, RSA, and RSI. It can be geographically visualized and analyzed, such as through heatmaps or hotspot analysis as shown in figure 4 (see Annex 3 for additional examples and descriptions). Telematics data has also been used to assess driver behavior, facilitate the prediction of crash-prone locations, and create geographic visualizations, as discussed in interviews with researchers at the ARRB and Professor George Yannis from the National Technical University of Athens. However, data privacy is an especially important concern when it comes to the use of telematics data.²⁷

²⁷ Anthony Germanchev (Principal Professional Leader, Advanced Technologies Lab, Australian Road Research Board) and Professor George Yannis (School of Civil Engineering, National Technical University of Athens), in discussion with the authors, April 2021.
Mobile applications are helping overcome underreporting of road crashes by crowdsourcing incident reports. For example, in Kenya, road crashes have been shown to be largely underreported, especially in areas where incident reporting mechanisms are lacking or underdeveloped.28 Navigation applications such as Waze are providing a valuable new source of crash and traffic data by allowing users to report incidents through their smartphone applications. Each incident report submitted by a user is geolocated and timestamped, which allows it to be combined with other geospatial data to identify segments of a road that are experiencing major or minor crashes, light to stand still traffic jams or hazardous conditions (hazards on the road or on the shoulder, weather alerts or dangerous road surfaces). Additionally, social media platforms like Twitter are used by many people on the ground to report on crashes and traffic conditions and can be leveraged using machine learning algorithms to produce additional data on crashes, as was done by the smarTTrans team in Nairobi.29 Lastly, mobile application data can be generated in real-time to assist with monitoring or collected and analyzed over time to develop models.

A growing number of countries and regions are focusing on developing a big data infrastructure to collect official incident reports. Collecting comprehensive and accurate information about road incidents is an important objective for government transportation agencies. There is growing inter-

28 Guadalupe Bedoya Arguelles, et al., “Smart and Safe Kenya Transport (SMARTTRANS).”
29 Sveta Milusheva et al., “Applying Machine Learning and Geolocation Techniques to Social Media Data (Twitter) to Develop a Resource for Urban Planning.”
est in gathering and analyzing the information in big data formats to provide deeper and more comprehensive insight into road safety risks and the impact of different interventions. The collection of real-time data would also be beneficial for this purpose, for which collecting, storing, and analyzing the information as big data would be most realistic and feasible.

**How to Access Big Data**

**Big data for road safety generally falls into two categories: public sector and private sector.** Traditionally governments have collected and provided data for road safety analysis, such as police reports of crash incidents. However, alternative sources are becoming increasingly available as mobile apps are used to crowdsourced reports of roadside incidents and companies aggregate traffic speeds from proprietary mobile applications. Often data quality from such sources can vary significantly by location, with certain sources being more effective, reliable, and better developed in some regions compared to others. Road safety practitioners advised to use the list provided in Annex 2 as a starting point and find the most relevant data providers for the region(s) of interest that their project focuses on.

**This Guidance Note focuses on big data sources that are most easily and readily accessible for road safety analysis.** Different sources require different approaches to obtaining relevant data quickly and efficiently. It is important to understand the licensing restrictions that accompany each source. For example, even though a dataset is crowdsourced, it may have licensing restrictions. It is best to consult a legal advisor and the data provider to clarify terms of use when necessary.

**Public sector.** Governments can collect, manage, and share data relating to transport, infrastructure, and mobility. Many governments, whether at the national level or even local municipalities, are establishing open data platforms where datasets can be accessed by running a simple search query. Such platforms have already been created in the Philippines as well as in Australia and the United States.30 In other instances, particularly where the data infrastructure is not as advanced, data may have to be requested through the relevant department. It is often possible to obtain datasets relating to crash histories or collected by road sensors from government sources which are extensive enough to be processed as big data in road safety analysis.

**The World Bank’s Road Safety Observatories (RSO) initiative also has the potential to become an important source of government-generated big data in the future.** The Observatories provide a formal network of government representatives to share and exchange road safety data and experience in order to improve road safety throughout the region. The World Bank established its first RSO in Latin America (OISEVI), before introducing the initiative in Africa (ARSO) and Asia-Pacific (APRSO). By enhancing road safety data and information systems, the Observatories play a pivotal role in helping countries monitor, evaluate, and develop more impactful road safety policies and interventions.31

**In other cases, publicly available datasets with a global reach may be considered.** A good example of this is OSM, which offers freely available geographic data generated by volunteers who trace satellite images around the world to create and update the map consisting of road networks (detailing road

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types, bridges, tunnels, direction of traffic flow), among other features. OSM data can be combined with other datasets for road safety analysis. While OSM provides an overview of the road geometry, the recency and accuracy of the data requires validation. Due to variability in quality and coverage, OSM data would be considered a starting point and is not recommended for detailed assessments.

**Private sector.** Mobility datasets are generated through ride-hailing services, delivery services, social media, and other mobile applications that collect user location and movement. Companies in the transportation and logistics sector use smartphone applications to digitize their operations and take advantage of higher quality, real-time data to improve efficiency as well. Other companies provide telematics software to track vehicle movement and safety features. Companies and start-ups investing in autonomous vehicle research are providing valuable sources of big data for road safety analysis. Some companies also provide APIs that allow developers to access these datasets (often on a limited basis). However, proprietary or commercial data may have to be purchased in some instances, or data partnerships need to be established to access such data. It is also crucial to understand how the data is licensed and can be legally used for different types of analysis. For example, Google restricts digitizing and tracing information as well as using applications to analyze and extract information from street view images, although annotation and labelling is permitted.\(^32\)

**Data Partnership Agreements.** Road safety practitioners can access various datasets for road safety analysis through data partnership agreements with companies. Practitioners can directly contact companies to request data relevant to road safety and, upon signing a licensing agreement, receive the data. Practitioners can also leverage data sharing platforms such as the Development Data Partnership (DDP), which is accessible to practitioners affiliated with certain international development

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organizations. DDP is a formal collaboration of private sector companies and select international organizations to use third-party data in research and international development.\(^{33}\)

**The Waze for Cities program is one example of a data sharing agreement that can be leveraged through direct contact with the company or, if accessible, through DDP.** The program allows cities to utilize data standards designed by Waze for closure and incident reporting to reduce data fragmentation and promote transport and government data aggregation. It now has more than 500 global partners including city, state and country government agencies, nonprofits and first responders. Another example of a possible data provider for road safety analysis is Moovit, an app focused on public transport, offers Mobility as a Service (MaaS) solutions for cities, providing personalized apps, payment solutions, real-time transit information, and other analytics.

**In many cases, data providers help local governments by exchanging data.** For example, the city of Tokyo in Japan has partnered with a private firm to develop a smartphone compatible app, Zenryoku Annai!. The app analyzes nearly 360 million observations every second to generate real-time information on the shortest and least-congested travel routes. A similar intelligent transport system (ITS) in Denmark, Copenhagen Connecting, was implemented to promote transport sustainability through real-time digital traffic control and weather adaptation options. Road safety practitioners should consider seeking the support of local governments to establish data partnership agreements, particularly if the datasets are not accessible through DDP.

**Data marketplaces.** Business leaders are keen to explore the value of the big data they collect as a tradable commodity. This has given rise to data marketplaces which are essentially online platforms dedicated to the buying and selling of data. These marketplaces can provide a more cost-effective source of data compared to other data mining techniques. Dedicated marketplaces for traffic and transport data have also emerged in recent years, although their coverage of LMICs tends to be low.

**As part of its efforts to establish an artificial intelligence tool for road safety analysis (called Ai-RAP), iRAP is seeking to establish a data marketplace where public and private data providers can trade data for road safety analysis.** The data marketplace will focus on three types of data products, according to Monica Olyslagers (Safe Cities and Innovation Specialist at iRAP), who was interviewed for this Guidance Note.\(^{34}\) The first is raw datasets that need to be processed to extract relevant information. The second is datasets that have been at least partially cleaned up and processed by data providers or Ai-RAP and are ready to be plugged into road safety assessments. The third is prepared-for-purpose datasets that are specifically commissioned for road safety assessments in different types of projects. This data marketplace model is currently being piloted in Africa, as part of a project to set up a regional road safety observatory there in collaboration with the World Bank.

**The new data marketplace will initially focus on aggregating and trading conventional datasets.** However, the project team plans to bring on big data providers and incorporate ML in the Ai-RAP tool to allow for more sophisticated analysis in road safety assessment procedures. Road safety practitioners are advised to search data marketplaces as a lesser-cost alternative to commissioning data collection for their projects.

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33 Development Data Partnership, [https://datapartnership.org/](https://datapartnership.org/)

34 Monica Olyslagers (Safe Cities and Innovation Specialist, iRAP), in discussion with the authors, April 2021.
Key Considerations for Selecting the “Right” Big Data Source

This section provides an overview on how different big data sources can be used. The data sources covered in table 4 for each method or assessment type should be viewed as guides, rather than concrete, all-inclusive lists. The most appropriate choice of data sources should eventually be determined by considering the costs and benefits of each source. A list of factors that may be useful to consider for this purpose are discussed toward the end of this section. It is also worth noting that while big data may not be a feasible alternative to conventional data for every project or assessment (if only at present), it can still complement and supplement current approaches or be used to validate their outcomes and analyses.35

<table>
<thead>
<tr>
<th>TYPE OF DATA REQUIRED</th>
<th>WHICH METHODS IT'S USED FOR</th>
<th>POTENTIAL BIG DATA SOURCE</th>
<th>EXAMPLES</th>
</tr>
</thead>
<tbody>
<tr>
<td>Crash data from 3–5 years</td>
<td>Methods I, V and VI</td>
<td>Government</td>
<td>Government portal or contact</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Mobile applications and telematics</td>
<td>Waze</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Crowdsourced</td>
<td>Waze</td>
</tr>
<tr>
<td>Operating speeds</td>
<td>Methods II to IV</td>
<td>Mobile applications and telematics</td>
<td>Mapbox, Waze</td>
</tr>
<tr>
<td>Road features (road markings, signs, traffic calming measures, etc.)</td>
<td>Methods III, V, VI, and VII</td>
<td>Street view imagery</td>
<td>Mapillary</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Crowdsourced</td>
<td>OSM</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Aerial and satellite imagery</td>
<td>Maxar, UAV</td>
</tr>
<tr>
<td>Road type (urban road, pedestrian area, etc.)</td>
<td>Methods III, V, VI, and VII</td>
<td>Street view imagery</td>
<td>Mapillary</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Crowdsourced</td>
<td>OSM</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Aerial and satellite imagery</td>
<td>Maxar, UAV</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Mobile applications</td>
<td>Orbital Insight</td>
</tr>
<tr>
<td>Vehicle fleet mean speed</td>
<td>Methods III to VII</td>
<td>Mobile applications and telematics</td>
<td>Mapbox, Waze</td>
</tr>
<tr>
<td>Traffic flow</td>
<td>Methods IV to VII</td>
<td>Traffic imagery</td>
<td>Mapillary</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Aerial and satellite imagery</td>
<td>Maxar, UAV</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Mobile applications and telematics</td>
<td>Mapbox, Waze</td>
</tr>
</tbody>
</table>

SOURCE: Original table for this publication.

As a broader variety of big data sources become available, road safety practitioners are advised to carefully consider the trade-offs involved when collecting data from various sources. The factors noted below do not provide an exhaustive list. Some factors may be more relevant to some projects than others, while additional considerations may be required for certain projects. In some cases, data from existing sources may not be available and will need to be collected using cameras, sensors, and/or other tools.

- It is worth noting that many of these factors are also interrelated. For example, the types and quantity of data required could impact costs of obtaining and processing it. Costs can also vary by region, as can the availability of resources to process and analyze the data. This list may be used in tandem with Annex 2, which provides an overview of the most relevant big data sources for road safety analysis as well as their relative costs, data attributes and formats, and possible limitations.

• **Type of road safety assessment or procedure.** As discussed in Part 1, a broad range of tools and procedures are used for road safety assessments. Each tool has its own specific data requirements. It is important to consider these before determining appropriate big data sources to complement analysis.

• **Context/Region(s) of Interest.** The types and variety of big data sources available can vary greatly from region to region, country to country, or even different provinces or localities within the same country. For example, Waze crowdsourced crash data is especially useful for urban regions that are more densely populated compared to rural regions.

• **Type of data required.** As more big data sources become available for road and traffic data, road safety practitioners carefully consider which variables and data types are most relevant to their model before selecting a source. For example, Google offers a number of APIs that may be useful for road safety analysis. This includes Google Maps, Google Traffic, and Google Street View. It is important to consider the quantity, duration, and extensiveness of the data required. For example, some data sources include time-series information, others do not. Some may include specific road features or road user data, while others may just be focused on traffic flows.

• **Data formats.** Big data is collected, stored, and transmitted in a wide range of formats. It is important to consider the usability of available big data formats as well as their interoperability with other types of data. Since many big data sources that are currently available are not custom designed for road safety analysis, it may be necessary to invest in resources and skilled expertise to extract, aggregate, clean, and convert the data into a format that can be combined with other data and/or used with analytical tools and models.

• **Cost.** Given the size of big datasets, costs can arise from accessing, storing, handling, processing, and analyzing the data. The cost may be in the form of data licenses, software licenses or equipment (if the data is being collected specifically for the project at hand). Besides the cost of obtaining the data, it is also important to consider the cost of using it, such as by acquiring the necessary expertise, software tools and processing power for analysis. Annex 2 discusses the relative costs associated with using different big data sources.

• **Resources required to make data usable.** In addition to relevant data sources and the costs that may be associated with accessing them, other resources could also be required to utilize the data in road safety assessment and analysis. This includes technical skills and expertise required to handle and analyze the data.

• **Time constraints.** Some big data sources are faster to access and obtain data from compared to others. For example, open data platforms allow you to run a search query and instantly obtain relevant datasets. Other avenues, such as data sharing agreements, may take longer to deliver the required data. It is important to consider the project timeframe to determine which data source may be more useful for road safety analysis at a given stage.

• **Licensing constraints.** Any official and legitimate data source is accompanied by licensing regulations that outline the terms of use of the provided dataset. Big data sources are no exception. Different data sources have different licensing agreements associated with them. Some, such as open data platforms, may have minimal licensing restrictions. Others, such as APIs and datasets obtained through data partnership agreements, can have more restrictive terms of use. It is important to carefully consider these limitations before choosing a source. Road safety practitioners are advised to consult legal advisors or the data provider to fully understand licensing restrictions associated with different big data sources to avoid legal ramifications.
2.2 Machine Learning in Road Safety Analysis

ML is a branch of artificial intelligence. It involves creating algorithms that “learn” patterns, trends and behaviors from data and improve accuracy over time without further programming. As figure 5 illustrates, the lifecycle of an ML model can be typically divided into two phases: training and deployment. In the training phase, training data is fed into the algorithm to obtain a trained model. In the deployment phase, new input data is fed into the trained algorithm (or model) to predict the output.

As shown in figure 6, ML algorithms can be divided into three categories: supervised learning, unsupervised learning, and reinforcement learning. The specific tasks they are capable of and the corresponding algorithms that are most widely used for this purpose are also listed in table 5. One significant difference between these categories is the format and source of training data.

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**Figure 5: ML lifecycle**

- Training data
- Training the algorithm
- Trained model
- New input data
- Prediction

**Figure 6: Categories of ML and the tasks they can perform**

- **Dimensionality Reduction**
  - Structure discovery
  - Feature elicitation
- **Unsupervised Learning**
  - Big data visualization
  - Recommendations
- **Clustering**
  - Customer segmentation
  - Targeted marketing
- **Classification**
  - Fraud detection
  - Image classification
- **Supervised Learning**
  - Diagnostics
  - Weather forecasting
- **Regression**
  - Advertising popularity predictions
  - Estimating life expectancy
  - Market forecasting
- **Reinforcement Learning**
  - Real-time decisions
  - Game
  - Skill acquisition
  - Robot navigation

Source: Modified from https://randomtrees.com/data-science

Source: Modified from https://towardsdatascience.com/coding-deep-learning-for-beginners-types-of-machine-learning-b9e651e1ed9d
Supervised learning is a family of algorithms that learn from previous data to map an input (X) to an output (Y). For example, a supervised learning algorithm can be used to predict the risk level or crash frequency (Y) of a road segment given its characteristics (X). “Supervised” means the training data is labelled (i.e., the training data should be pairs of X-Y, where Y is usually called labels).

Unsupervised learning algorithms find structures in a dataset in order to group or cluster data points based on their similarity. As the name suggests, these algorithms do not require “supervision” or human intervention in the training phase. This means that, unlike supervised learning, the training data for unsupervised learning algorithms has no labels (Y). These algorithms learn to group X based on similar characteristics. The most common unsupervised learning task is clustering. For example, given the characteristics of a road segment, an unsupervised learning algorithm can classify it into a group of similar segments. It does not need to understand the characteristics that the group represents to complete this task.

Reinforcement learning trains a software agent to make decisions that maximize rewards from interactions with an external environment. As opposed to supervised learning and unsupervised learning, which require training data to be prepared before training, reinforcement learning generates the training data during the training phase. The data is generated when the agent interacts with the environment. For example, reinforcement learning can be used to train an agent to control traffic lights based on traffic conditions.

<table>
<thead>
<tr>
<th>TABLE 5: Categories of ML and algorithms*</th>
</tr>
</thead>
<tbody>
<tr>
<td>ALGORITHMS</td>
</tr>
<tr>
<td>Supervised Learning</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Unsupervised Learning</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Reinforcement Learning</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>

Source: Original table for this publication.

Artificial neural network (ANN) is a family of ML algorithms that have been inspired by the human brain. ANN is the most versatile ML algorithm – it can be used for supervised learning, unsupervised learning, and also reinforcement learning. As shown in figure 7, ANN structures the data and the computation in different layers. Every layer adds more depth to the algorithm; therefore, more layers indicate that it is “deeper”. Such ANNs are called deep neural networks or deep ANN or DNN. ML algorithms that use deep ANN are called deep learning (DL) algorithms. Therefore, from another perspective, ML algorithms can be divided into conventional ML and DL (table 6).

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36 This agent is a piece of software that makes a decision based on the environment.
Most ML algorithms are conventional ML, such as conventional supervised learning algorithms like support vector machine (SVM), which can be used for classification or regression, for example, classifying the risk level of a road segment based on its characteristics. Conventional unsupervised learning algorithms, such as K-means clustering, automatically identify spatial patterns in datasets, which can be applied to locate clusters or areas with recurring road crashes. Conventional ML works well for small, low dimensional datasets. Meanwhile, DL is a subset of ML that learns the complex patterns from high dimensional (e.g., an image) and large quantities of data (e.g., big data). Supervised, unsupervised, and reinforcement learning algorithms that use deep ANN technique belong to the deep learning category. DL’s first successful application is in the computer vision area. For example, image classification is a supervised learning task that utilizes deep neural networks to classify images into different classes (e.g., cars, pedestrians, etc.).

### How to Use Machine Learning

The use of ML methods in road safety analyses is being widely explored. As ML methods become more advanced, economical, and accessible, their potential applications in various disciplines continue to grow and become more feasible. In road safety analyses, ML has great potential to overcome the limitations of traditional statistical models in crash analysis and crash probability modeling. The applications of ML in road safety analyses are discussed under three categories: conventional ML, DL, and reinforcement learning, as listed in table 7. It should be noted that some reinforcement learning algorithms using deep ANN belong to DL, but all reinforcement learning techniques are discussed separately.

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**TABLE 6: ML and DL algorithms**

<table>
<thead>
<tr>
<th></th>
<th>CONVENTIONAL ML*</th>
<th>DL</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supervised Learning</td>
<td>SVM, DT, RF, KNN, shallow ANN</td>
<td>Deep ANN</td>
</tr>
<tr>
<td>Unsupervised Learning</td>
<td>K-means, PCA</td>
<td>Deep ANN</td>
</tr>
<tr>
<td>Reinforcement Learning (RL)</td>
<td>RL without deep ANN</td>
<td>RL with deep ANN</td>
</tr>
</tbody>
</table>

*The conventional ML algorithms listed in this table are not exhaustive.*

**FIGURE 7: ANN structure**

[Diagram of an artificial neural network (ANN) structure with inputs, hidden layers, and outputs.]

**SOURCE:** Original figure for this publication.

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A growing body of research explores various ML techniques to predict the probability of road crashes and assess their severity by training on historical datasets that encompass diverse factors. Conventional ML algorithms are the most frequently used ML algorithms for this purpose. They are summarized in table 7. ML-based approaches to road safety analysis can be used to complement, supplement or even potentially substitute conventional road safety assessments.

Conventional supervised learning algorithms learn functions that take vectors of variables as input to predict the output. Most conventional supervised learning algorithms that are frequently used in data science have been used in road safety analyses, including but not limited to: decision trees (DT), random forest (RF), support vector machine (SVM), k-nearest neighbors (KNN), and artificial neural networks (ANN). It should be noted that there is no “best” algorithm. Determining which algorithm may be most appropriate for an ML-based road safety analysis is essentially a data science problem for which there are usually no set rules. One algorithm may perform well for a dataset, but badly for another. It is common practice for data scientists to try different algorithms in order to find a suitable one for a specific problem. When using the aforementioned conventional supervised learning algorithms for road safety assessments, the problem is often framed as a classification or regression problem, in which the output (Y) of the ML algorithm is either a class (e.g., risk level or severity: low, moderate, substantial or high) or a scalar (e.g., crash probability, crash frequency) and the input (X) to the ML algorithm could be any parameter (including but not limited to weather, time, road factors, human factors, etc.) that is related to the output.

Conventional unsupervised learning algorithms are mainly used for clustering and dimensionality reduction purposes. In road safety analyses, K-means can be used for grouping tasks that help find clustering patterns in the data. For example, it can be used to group road segments by similar characteristics or group drivers based on their driving behaviors, so that dangerous road segments or drivers can be identified based on the similarity. In another example of unsupervised learning ap-

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**TABLE 7: Frequently used ML techniques for road safety analysis**

<table>
<thead>
<tr>
<th>ML CATEGORIES</th>
<th>SUBCATEGORIES</th>
<th>ALGORITHMS</th>
<th>TASKS</th>
<th>EXAMPLES</th>
</tr>
</thead>
<tbody>
<tr>
<td>Conventional ML</td>
<td>Supervised Learning</td>
<td>SVM, DT, RF, KNN, shallow ANN</td>
<td>Classification</td>
<td>Predict risk level based on road characteristics.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Regression</td>
<td>Crash frequency prediction based on road characteristics.</td>
</tr>
<tr>
<td></td>
<td>Unsupervised Learning</td>
<td>K-means</td>
<td>Clustering</td>
<td>Group road segments by characteristics similarity; group drivers based on their driving behaviors.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>PCA</td>
<td>Dimensionality Reduction</td>
<td>Identify critical factors of road safety.</td>
</tr>
<tr>
<td>DL</td>
<td>Supervised Learning</td>
<td>CNN</td>
<td>Image Classification/Object Detection/Segmentation</td>
<td>Detect road features from images.</td>
</tr>
<tr>
<td></td>
<td>Unsupervised Learning</td>
<td>GAN</td>
<td>Clustering/Dimensionality Reduction</td>
<td>Find the hidden features related to road safety from map and satellite images of the road environments.</td>
</tr>
<tr>
<td>Reinforcement Learning</td>
<td>N/A</td>
<td>Q-Learning/DQN</td>
<td>Robotics/Decision-making</td>
<td>Control traffic lights based on traffic conditions.</td>
</tr>
</tbody>
</table>

*The algorithms and examples listed in this table are not exhaustive. CNN: convolutional neural network, a type of deep ANN GAN: generative adversarial networks, a type of deep ANN

**SOURCE:** Original table for this publication.

application, principal component analysis is used for reducing the dimensions of input data to identify the most critical factors that affect road safety.

**DL has been applied in various disciplines and achieved impressive performance.** DL technologies have progressed significantly over the past few years, especially in image analysis and computer vision, the method’s first successful application. The core technique in this domain is deep convolutional neural network (CNN), which is the state-of-the-art approach for object detection, semantic segmentation, and instance segmentation of images. Object detection is a task in which, given an image, the model outputs a bounding box of detected objects (figure 8). Semantic segmentation is a task in which, given an image, the model classifies every pixel into predefined classes (e.g., road lane, traffic light, etc.). Instance segmentation is a task, in which, given an image, the model groups pixels belonging to an instance of the object.

**FIGURE 8: ML algorithms and street view**

After applying an object detection algorithm to a street view image, a bounding box surrounds each predicted object, which also contains a confidence level for each prediction.

*DL-based image analysis has been successfully used in various industries for applications ranging from facial recognition to autonomous driving.* It has great potential to be used in road safety analysis to automatically analyze images and infer road attributes that are relevant to road safety assessments. Large sets of images with annotations such as road lanes, traffic lights, speed limit signs, and pedestrians can be compiled for training deep CNNs so that they learn to recognize these objects through images that the models have not previously encountered. If successful, this approach should equip the model to detect road attributes at a regional scale.

**The detected information can then be used for safety and risk analysis.** For example, if the DL model can infer the road segment characteristics (e.g., number of lanes, terrain type, road markings and signs, and pedestrian, bicycling, and motorcycling facilities), the inferred information can readily be
used as input for various road safety assessment tools. This would allow the process of detection and analysis to become fully, or at least significantly automated and scalable at a low cost.

**DL can also provide a lower-risk alternative to manual detection of certain road attributes and other important variables in road safety analysis.** For example, a team used imagery from Baidu Street View to provide a practical, automated alternative to the manual detection of street cracks, which can be labor-intensive, hazardous, and difficult to conduct on a large scale. The authors use the Deeplabv3+ network model, a DL neural network, to develop an automated road crack identification system and demonstrate its practicality as a method to generate faster, more accurate and efficient information about road cracks at lower cost compared to manual detection.39

**Reinforcement learning is widely used to design intelligent control and decision-making systems.** In road safety and traffic management, reinforcement learning is most commonly employed to develop intelligent signal control algorithms. A typical reinforcement learning-based traffic light system makes divisions based on specific input traffic parameters, such as the length of time for which vehicles wait at the intersection, the cumulative delay caused by waiting at the intersection, the length of time for which the light stays green for each signal head, etc. The output of the system would be the next color of the light and length of time for which it should remain switched on. Designing traffic systems using reinforcement learning helps save time and improve safety standards.

**Key Considerations for Using Machine Learning**

**Road safety can be evaluated explicitly using rule-based reasoning systems.** However, developing such systems can be complex if there are many input variables. Compared with rule-based evaluation systems, ML algorithms are data-driven and don’t require developing rules; therefore, they are relatively inexpensive to implement. ML algorithms are more suitable for high dimensional inputs. As a broader spectrum of ML algorithms become available, road safety practitioners are advised to carefully consider the trade-offs involved when applying them to road safety analysis. This section discusses various factors that must be considered before deciding to use an ML algorithm for road safety analysis in their project. Again, this is not an exhaustive list. Some factors may be more relevant to some projects than others, while additional considerations may be required for certain projects. It is worth noting that many of these factors are also interrelated. For example, the feasibility of using ML for a project can be affected by time and budget constraints, the availability of data and the anticipated resource intensiveness of the data preparation process. Table 8 provides a SWOT analysis of the use of ML in road safety analysis.

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### TABLE 8: SWOT analysis of using ML in road safety analysis

<table>
<thead>
<tr>
<th>STRENGTHS</th>
<th>WEAKNESSES</th>
</tr>
</thead>
</table>
| - Offers tools and techniques to process big data that may be more precise compared to traditional methods.  
- Especially effective for feature learning, parameter optimization, and processing large amounts of big data.  
- ML algorithms tend to perform better than traditional statistical techniques in cases where high-dimensional and high-nonlinear data is involved.  
- As the technology develops, novel techniques create new opportunities to understand complex relationships between multiple, interrelated variables and predict outcomes with greater accuracy.  
- ML algorithms can be improved continuously as more data is generated or made available for training. | - Algorithms can be limited in their applicability; models may not perform well on data that is different from the training data’s distribution.  
- Large amounts of data are needed to train the models and yield more accurate models, which may be difficult in data-scarce contexts.  
- Some ML algorithms (e.g., ANN) work like a black box, and can be hard to interpret, therefore an ML algorithm usually requires thorough validation and test processes before it can be deployed in the real environment and assist decision-making.  
- The technology still needs further development before it can be mainstreamed for use in road safety assessments. |

<table>
<thead>
<tr>
<th>OPPORTUNITIES</th>
<th>THREATS/CHALLENGES</th>
</tr>
</thead>
</table>
| - May eliminate the need for manual coding of road safety data in the future, making the process less labor-intensive and time consuming.  
- Possible to train datasets in one location or for one purpose and use them for another.  
- Provides a powerful method for complex crash risk modelling and other types of predictive analytics in road safety.  
- As the technology develops, a platform powered by ML could be used across geographies for road assessments.  
- As more and more data is generated and collected everyday, this could be potentially analyzed with ML algorithms to discover new patterns and insights. | - Requires specialist expertise, tools, and knowledge which may make its usefulness limited in some contexts, especially in developing countries.  
- May require additional investment in computer power and analytical software.  
- Complexity of ML algorithms can make them difficult to implement and analyze.  
- Ethical considerations, such as bias in ML systems.  
- As a data-driven approach, ML relies on high-quality data for training. Significant bias in the training data could lead to the failure of model training. Quality control of training data could be difficult, especially when annotating the data requires professional knowledge. |

**Feasibility with project objectives and client requirements.** Before deciding to use ML for any project, it must be ascertained if ML is suitable for the project. Some ML algorithms, such as neural networks, are not interpretable. They work like a black box. Clients may not have confidence in using them for significant decision-making unless their predictions can be sufficiently validated.

**Preparing data to train ML algorithms.** ML is a data-driven approach. Therefore, as with any data-related project, it is important to plan the data collection and preparation process. To facilitate this process, make sure to have clearly defined the inputs and outputs of the model at the outset of the project. Section 2.1 provides guidance on how to select data sources, especially where big data may be involved. It is common that, during the training stage, an ML team may find the data is not enough to train a model with satisfactory performance. In this case, more data needs to be collected. In terms of data preparation, teams should be aware of the need to aggregate, clean and annotate data before it can be used for ML modelling. Annotation of data is especially necessary for supervised learning algorithms and entails manually identifying an object drawing a box or polygon around it and giving it a label such as “pothole” or “crosswalk” (figure 9).
Teams are advised to incorporate a quality control process to ensure data being used for any ML model, especially test data, is of good quality and truly valid and representative of the population or situation under study. For an ML-based project, steps include: (i) identifying data required for the model; (ii) data collection, cleaning, annotation; (iii) trial and error training; (iv) validation; (v) deployment. It is advisable to estimate the duration of these tasks, their expected complexity and potential challenges (which can vary by context and availability of resources such as expertise and processing power) before deploying ML in any project. This helps determine if ML is feasible, how it compares to traditional methods and how incorporating ML can impact project timelines. It is worth noting that once deployed in the production environment, ML provides significant acceleration for the whole process, for example, DL-based image analysis can exponentially save the time for collecting data to be used in the road risk estimation.

A challenge for most ML algorithms is generalization, or how well a model can perform based on test data (also called unseen data). Models may not perform well on unseen data that is different from the training data’s distribution. For example, a model that is trained on images collected on rural roads in an arid climate may not achieve the same level of performance on images in urban roads in another country. The transferability of the model depends on how similar the features in the images are. Therefore, before training ML algorithms, it is prudent to consider the diversity of the training data, especially in terms of where, how and when it was collected. It is worth noting that some researchers have found that artificial intelligence and ML algorithms can be easily and accurately applied to different types of urban networks within the same city.40

To determine if using ML fits a budget or can even deliver a cost-advantage, it is important to understand associated costs. Costs of using ML can arise from the hiring of experts to develop and program models, as well as from the data collection and preparation process (which includes cleaning

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and annotation). The cost of storing data (on local hardware or on the cloud) should also be accounted for, especially if the inputs involve big data. Depending on the model and quantity of data being input, and especially if a DL model is employed, you may also need to invest in additional computational resources (graphics processing unit-equipped local computers or nodes on the cloud). Front-end and back-end systems may also need to be established for automatic analysis services.

**Deploying ML algorithms requires specialized expertise, often in the form of dedicated team members that are ML experts.** These may be addressed by hiring experts and managing the process internally or acquiring resources externally. An in-house, “do-it-yourself” approach ensures more control over every aspect of the process, which may be especially important where significant customization or trial and error may be required. However, this approach requires labor and time, and may be more costly in the long run. Using an external resource or tool, on the other hand, may be a faster option but can come at the expense of some visibility and control over the development of the model. It is important to consider these trade-offs to ensure the team is adequately resourced to use ML effectively in the project.

### 2.3 Big Data, Machine Learning and the Future of Road Safety Assessments

Artificial intelligence presents many exciting possibilities for automation and analysis in transport and infrastructure development. ML is increasingly used for road safety analysis. ML’s inherent capability of managing uncertainties in data and models makes it extremely suitable for solving road safety related issues. Uncertainty is a defining element of crash risk modelling and, in fact, a source of complexity that has thus far limited the usefulness of traditional statistical models. Moreover, ML algorithms such as deep ANN can capture nonlinear patterns in data, making them the first choice for processing road safety big data. Table 9 provides a summary of possible applications of big data and ML in road safety analysis given the current state of the technologies.

#### TABLE 9: Potential applications of big data and ML in road safety analysis

<table>
<thead>
<tr>
<th>POTENTIAL APPLICATIONS</th>
<th>HOW BIG DATA CAN HELP</th>
<th>HOW ML CAN HELP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Estimating Road Infrastructure Risk</td>
<td>Video and photo images, APIs, satellite imagery and/or crowdsourced images</td>
<td>• Process images to evaluate road attributes&lt;br&gt;• Identify road features that could cause crashes&lt;br&gt;• Identify risk factors contributing to crash occurrence&lt;br&gt;• Identify safety conditions in infrastructure</td>
</tr>
<tr>
<td>Traffic Flows</td>
<td>APIs, aerial imagery, open-source traffic data, road sensor data, wireless technology, street cameras, GPS data, mobile devices, real-time traffic data</td>
<td>• Process images to classify vehicles, identify congestion hotspots, vehicle detection, or speeds&lt;br&gt;• Assess traffic flows&lt;br&gt;• Develop risk maps&lt;br&gt;• Map the safety performance and Star Rating&lt;br&gt;• Traffic flows prediction</td>
</tr>
<tr>
<td>Crash Risk Assessment</td>
<td>Meteorology data, geo-located crash data, video and photo images, APIs, open-source traffic data, road sensor data, historical crash data, crowdsourced crash data (e.g., Waze)</td>
<td>• Create crash prediction models&lt;br&gt;• Develop risk maps&lt;br&gt;• Analyze different conflict scenarios and high-risk behavior</td>
</tr>
<tr>
<td>Incident Reporting/Crash Data</td>
<td>Video recording, crash data, photo images, crowdsourced data (Google Maps, Waze)</td>
<td>• Identify hotspots through clustering techniques</td>
</tr>
<tr>
<td>Analyzing Crash Severity</td>
<td>Video and photo images, sensor data</td>
<td>• Process images to evaluate road attributes&lt;br&gt;• Develop crash prediction models</td>
</tr>
</tbody>
</table>

*SOURCE: Original table for this publication.*
Combining big data and ML can provide an integrated framework for automatic road safety analysis and management. This framework, demonstrated in figure 10, employs platforms (such as Mapillary) to provide geo-tagged street level imagery for inputs to the DL model to infer useful information (e.g., road characteristics). The DL-inferred data is then combined with multi-source big datasets (e.g., region-specific historical crash data) for better analysis and management of road safety.

**FIGURE 10:** Framework for automatic road safety analysis and management powered by ML

At present, much of the research and innovation in the use of ML for advanced road safety and risk modelling is being driven by universities and other research institutions. As other stakeholders, such as road safety practitioners, governments, developers of road safety tools and international organizations such as the World Bank look to apply ML in their projects, there is an opportunity to create dedicated tools that would harness big data and ML for road safety analysis. Such applications have the potential to reduce the risk of human error and allow road safety assessments to be mostly, if not fully, automated.

The following section presents practical examples of how big data and ML can assess urban road safety. It applies an integrated framework introduced in section 2.3 to explore the opportunities and limitations of new data sources and assess the ML models. To evaluate the robustness of the proposed framework, the Integrated Framework for Road Risk Prediction was applied in two cities of different sizes, regions, and data availability were chosen: Bogotá, Colombia, a rapidly urbanizing metropolis in Latin America, and Padang, Indonesia, a secondary city in East Asia. The study found that ML applied to street view imagery identified relevant road (and road user) characteristics to generate a model that predicts road risk with 72.5 percent accuracy in Bogotá. This framework was applied in Padang to test its replicability; preliminary results are encouraging for its potential to predict road safety for areas with limited crash data. The section concludes with a reflection and guidance for replicability.
PART 3
Case Studies: Applying Big Data and Machine Learning to Assess Road Safety

3.1 Objectives of the Case Studies

This section presents how the Integrated Framework for Road Risk Prediction can be applied in two different cities of interest: Bogotá, Colombia and Padang, Indonesia. The study examines how useful ML is in evaluating road safety and how easily the integrated framework can be replicated. All code is freely available for other teams to use and develop further.\(^1\)

The objectives of the case studies are to:

1. Learn how well big data and ML can be used to identify road features, estimate road safety, categorize road segments based on their risk level, and identify high-risk segments.
2. Evaluate the utility of several big data sources that are freely available for road safety analysis in diverse geographic areas.\(^2\)
3. Assess the replicability of the proposed approach.

Located on two different continents, the selected locations offer an opportunity to apply the framework on paved, urban roads in contrasting environments, particularly related to data availability and usability. For example, the government of Bogotá has made significant efforts to increase crash data collection and dissemination. The government offers an online portal with the location of each crash over the past year publicly available. In addition, there was high coverage for data derived from mobile phones, such as crowd-reported crashes. In contrast, information on the crash locations for Padang could not be found online, and methods for data collection are largely manual or paper based.\(^3\) In addition, mobile application data was scarce for crowdsourced crash reports. As a result, Padang offers the opportunity to explore the utility of ML when data coverage is limited.

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\(^1\) The code for the Integrated Framework for Road Risk Prediction is open source and accessible on GitHub: [https://github.com/datapartnership/IntegratedFrameworkForRoadSafety](https://github.com/datapartnership/IntegratedFrameworkForRoadSafety). However, some datasets require partnership with DDP to access.

\(^2\) Freely available meaning at no cost; however, some data sources are not publicly available and require a license.

BOGOTÁ AND PADANG: BACKGROUND AND CONTEXT

With a population of more than 7 million, the capital district of Bogotá is Colombia’s largest city. As a critical economic hub with a growing population, Bogotá stands out as one of the most congested cities in the world.\(^{44}\) The government has prioritized road safety and achieved significant gains over the past few decades, reducing the city’s traffic fatality rate by more than 60 percent between 1996 and 2006 alone.\(^{45}\) More recent interventions during the UN Decade for Action for Road Safety include establishing a National Road Safety Plan and a National Road Safety Agency (Agencia Nacional de Seguridad Vial) featuring a National Road Safety Observatory in collaboration with the World Bank.\(^{46}\) In addition, in 2017, the city’s government launched “Vision Zero,” which aimed to implement a range of speed management strategies to eliminate pedestrian and driver fatalities. The program has delivered measurable results, such as a 27 percent reduction in fatalities across corridors where speed limits have been introduced, and further interventions are planned to sustain its impact.\(^{47}\) Despite these initiatives and road safety improvements in Bogotá, challenges remain, and new policies would benefit from timely and affordable analytics on road safety.

Padang is the capital of the Indonesian province of Western Sumatra with a population of around 1 million. The government of Indonesia introduced various initiatives to address road safety during the UN Decade of Action for Road Safety. Established in 2011, the National Road Safety Master Plan achieved a 10 percent reduction in annual road fatalities between 2013 and 2016. However, data collection and management systems that rely on manual screening significantly challenge the country’s progress in road performance and safety.\(^{48}\) Initiatives such as the establishment of the Integrated Road Asset Management System and the World Bank’s new Asia-Pacific Road Safety Observatory present a valuable opportunity for the country to improve its road safety data systems.\(^{49}\) For this case study in Padang, crash data was scarce from alternative sources. Therefore, it offers the opportunity to explore the utility of the pre-trained ML models in a new region with limited data coverage.

\(^{44}\) INRIX 2018 Global Traffic Scorecard. In 2018, drivers lost 272 hours in road congestion.


\(^{48}\) World Bank, Indonesia Public Expenditure Review 2020: Spending for Better Results.

3.2 Methodology

The ML-based framework implemented in these case studies was developed to provide a quick screen to evaluate road safety. The framework ascertains road characteristics traditionally collected or annotated to provide a road safety prediction. ML models were developed specifically for this framework during these case studies, one to extract road characteristics from street view images and one to determine road risk based on the derived road characteristics. To do so, first, the models needed to be trained to extract road characteristics and determine the road risk based on crash data. Then the models could be applied to make predictions in new areas without crash data. Therefore, there were two phases in this framework, first the training phase to train the models (figure 11), and then the deployment phase to make new predictions with the models (figure 12). In each phase there were three steps, both of which began with data collection and preparation. OpenStreetMap (OSM), Waze, and Mapillary were used to develop this framework (additional examples of these datasets and related analysis can be found in Annex 3).

The OSM road network provided the foundation for analysis. It is freely available and scalable. OSM uses lines to represent roads and points to represent links among the roads. In OSM, the geometric road lines are split into road segments (called ways) that are connected by the points (called nodes). No modifications were made to the OSM geometry to maintain its synchronicity with other big datasets referencing OSM ways and nodes.

The Waze crash data consists of coordinates representing the location where users of the Waze application are when they see and report a crash.\(^{50}\) The Waze crash points were joined to the nearest OSM road segment (within 20 meters). For each road segment, the crash frequency, or crash per meter, was calculated to normalize the frequency of crashes. Since OSM road segments vary in length and there could be multiple reports per crash, calculating the crash frequency provided crash trends. To identify road segments with more frequent crashes per meter, the crash frequency was split into high and low risk.

Mapillary was used to obtain street view images, which were primarily collected by the World Bank’s Global Program for Resilient Housing. Since many images are captured along a street, and many images can be linked to a single road segment, the image closest to the centroid of the road segment was selected. The radius for this selection was within three meters of the centroid. This approach standardizes the image selection and classification: one image represents the scene of one road segment. For each OSM road segment, a street view image taken near the centroid of the segment was downloaded using Mapillary API v4.

\(^{50}\) Data provided by Waze App. Learn more at waze.com.
The Training Phase

The training phase consisted of two significant steps that were powered by ML to extract information from street view images and to make predictions on risk level based on extracted data. Each step had an ML model at its core that needed to be trained based on data. Therefore, there were three steps in the training phase.

Step 1. Select the region of interest and prepare data

A generalized polygon of the region of interest was used to collect data from OSM, Waze, and Mapillary. The road network database was prepared, and the street view images closest to the centroid of the road segment were downloaded as inputs for the models.

Step 2. Develop ML model for identifying road characteristics

The first custom ML model developed for this case study was the Road Information Collector (RIC), shown in figure 11. It is a deep convolutional neural network, Mask R-CNN, which can classify and count objects detected in images.\(^5\) The RIC model was trained with images from the updated Mapillary Vistas Dataset (initially released in 2017), which provides detailed characteristics for types of road markings and barriers, traffic lights and signs, and vulnerable road users such as pedestrians, motorcyclists, and bicyclists.\(^6\) Other identifiable characteristics include flat terrain, which characterizes road gradient, and the presence of potholes, which could indicate paved, urban road quality. The RIC takes street view images as the input and can detect more than 100 classes of objects as the output (for a complete list of the features the RIC model detects, refer to Annex 4). The model can

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detect and classify some road features better than others (for the precision score in detecting and classifying the objects, see Annex 5).

**Step 3. Develop ML model for evaluating road risk**

The second ML model developed was the Road Risk Evaluator (RRE). The RRE is a neural network classifier with two hidden layers; each has 50 neurons. The RRE was trained using paired data for each road segment, the road attributes from the RIC and the assigned road risk from the road network database. Similar work was conducted by a team using a neural network to predict the crash frequency of road segments.53

**The Deployment Phase**

Once the two ML models are trained, they can be added to an automated workflow in the deployment phase. This means the trained ML models can now predict the risk level for any road segment with the required input data – a street view image. Crash data is not required in the deployment phase.

![Deployment phase to predict road safety](image)

The deployment phase uses three steps to predict risk within an automated workflow (figure 12).

**Step 1. Select the region of interest and download data**

For the selected region of interest, the code will download the road network from OSM and calculate the centroid of each road segment. The code will then download from Mapillary API a street view image taken near the centroid of the road segment.

Step 2. Identify road characteristics

For each road segment, the downloaded image will be fed into the RIC to extract road characteristics. For each image, the RIC will output the numbers of detected objects for each class (refer to Annex 4 for classes). These numbers are put together to form a vector for each image.

Step 3. Evaluate road risk

Each vector produced by the RIC will be fed into the RRE to calculate the risk level: high or low. To illustrate the automated workflow of the deployment phase, figure 13 shows the risk prediction for a road segment. The RIC detected a flat road, car, and motorcycle; therefore, the RRE predicted the road segment as low risk. This framework requires no historical crash data to identify high- or low-risk roads.

The two case studies presented illustrate the training and deployment phases.

The training phase was conducted in Bogotá, where data was collected to train the ML model RRE, while the RIC model was trained on the Mapillary Vista Dataset. Then the models were applied in the deployment phase to predict the risk level for each road segment in Bogotá, Colombia.

The second case study was in Padang, Indonesia. The RIC and RRE models trained in the previous case study were applied directly (i.e., without re-training) in a deployment phase to predict road risk in Padang. This demonstrates that, ideally, there is no need to re-run the training phase for future applications since the RIC and RRE are already trained.
3.3 Case Study 1: Bogotá, Colombia

The Training Phase

Step 1. Select the region of interest and prepare data

In Bogotá, a road network database was created to prepare training data for the ML models. First, a
generalized polygon of the region was used to retrieve roads from OSM and six months of crash re-
ports from Waze (July–December 2020). The crashes were joined to the nearest OSM road segment
within 20 meters. The crash frequency, or crash per meter, was calculated and road segments were
divided into high risk (crash frequency >0.5) and low risk (crash frequency <=0.5) in the road network
database. This means a crash per meter of 1 represents one crash per meter in the six months of the
Waze data collected. Street view imagery was downloaded using the Mapillary API to collect images
close to the centroid of each road segment. Table 10 provides an overview of the data sources for this
case study.

<table>
<thead>
<tr>
<th>DATA SOURCES</th>
<th>ATTRIBUTES</th>
<th>REMARKS</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROAD NETWORK</td>
<td>OSM</td>
<td>Road network (road segment length)</td>
</tr>
<tr>
<td>CRASHES</td>
<td>Waze</td>
<td>Road alerts (crashes reported by users, coordinates)</td>
</tr>
<tr>
<td>ROAD CHARACTERISTICS</td>
<td>Mapillary (images and tags)</td>
<td>Street view image detections (crosswalk, curb, guard rail, human, marking, pothole, sidewalk, sign, streetlight, traffic sign, utility pole)</td>
</tr>
</tbody>
</table>

Step 2. Develop ML model for identifying road characteristics

The RIC was developed and trained to perform instance segmentation. It is a deep convolutional
neural network that identified the classes, or objects in the image, and provided the count of these
classifications. The model was trained using the Mapillary Vistas Dataset using a total of 124 classes
(Annex 4). The resulting output is a count of the classes identified by the bounding boxes, shown in
figure 14, which is represented through a series of integers.

Training data: Mapillary Vistas Dataset (124 classes)
Input: Street view image near the centroid of a road segment
Output: A vector of integers (each element represents the count of detected objects that belong to a class)

Figure 14 depicts the RIC in action on an image from Bogotá. The bounding boxes surrounding each
object in the image indicate classes the model identified. Confidence levels are provided next to the
name of the object segmented by the bounding box. The closer the confidence level is to 1, the higher
the confidence in the prediction. Looking at the center of the image, the bicyclist was identified with
0.5 confidence, and other vulnerable road users were recognized, such as a motorcyclist (0.84) and
pedestrian (0.75). Vehicles were segmented with high confidence for the bus (0.7), motorcycle (0.88),

54 G. Neuhold et al., “The Mapillary Vistas Dataset for Semantic Understanding of Street Scenes.”
and car (0.99). The RIC segmented traffic signs, support and utility poles, flat road, and road markings as well.

**FIGURE 14: Image segmentation in Bogotá**

The sample image shows favorable results for image segmentation. The performance of the RIC model in terms of the average precision of the bounding box detection and classification for each class is provided in Annex 5. In the next step, road attribute data extracted through the RIC were inputs for the prediction model to link the road characteristics with the likelihood of a crash in the road networks examined.

**Step 3. Develop the ML model RRE for evaluating road risk**

To develop the RRE, six study areas in Bogotá, Colombia were selected to reduce computational load. These study areas were drawn to include a wide variety of neighborhoods (poor, rich) and placed throughout the city. They also contain high and low crash frequency road segments and comprehensive street view image coverage. Figure 15 shows the six study areas along with the crash risk from the road network database, high risk (crash frequency >0.5) and low risk (crash frequency <=0.5).
The low- and high-risk road segments in these areas were the training data for the model. Based on the segment risk derived from the road network database and the characteristics for each road segment derived from the RIC, the model was trained to evaluate a road segment as high or low risk.

*Only 106 out of 124 classes are used as the input to RRE. A total of 18 classes irrelevant to road characteristics, such as sky, bird, etc., were removed from the vector before entering into the RRE.

In searching for an optimal architecture of the neural network, the number of layers and neurons were tested for the best performance. Testing showed that more layers or neurons do not significantly improve the performance on this dataset. The RRE was used to evaluate whether a road segment was low or high risk based on a street view image.

**Overall performance of the ML**

Predictions of low-risk road segments were correct 70 percent of the time, and predictions of high-risk road segments were correct 75 percent of the time (figure 16). The mean accuracy and F1-score were both 72.5 percent. The closer the accuracy and F1-score are to 100 percent, the better the performance of the model. In the case of this model, a random guess of a binary classification is 50 percent, which makes these results promising. These results suggest the model would perform well in similar contexts as Bogotá. If needed, there would be potential to fine-tune the model for increased accuracy and precision in other areas.
TIPS FOR INTERPRETING ML PERFORMANCE

The performance of an ML model can be evaluated using accuracy, precision, recall, and the F1-score. These are derived by counting the correct predictions (true positives and true negatives) and incorrect predictions (false positives and false negatives).

- accuracy = correct predictions / all predictions
- precision = true positives / (true positives + false positives)
- recall = true positives / (true positives + false negatives)
- F1-score = 2*((precision * recall) / (precision + recall))

A confusion matrix shows how well the model performed in predicting road risk through a comparative chart of the true positives, true negatives, false positives, and false negatives.

Bogotá Results

Following the three-step workflow of the deployment phase described in section 3.2, road risk was predicted for the entire road network in Bogotá. In total, 98,488 images were processed to make the predictions shown in figure 17. Road segments without an image within 3 meters were not predicted. Overall, high crash frequency from Waze and high-risk predictions exhibited similarity along some segments, particularly on arterial roads; however, the model tended to moderately overpredict high risk.
3.4 Case Study 2: Padang, Indonesia

The Deployment Phase

The model that was built in Bogotá was applied in Padang. Similar to Bogotá, the road network was accessed through OSM, and street view images were downloaded using the Mapillary API. Waze crash data was joined to the OSM road network to compare with risk predictions. Padang had limited geospatial crash data to validate the model. Table 11 provides a description of the datasets.

TABLE 11: Data used for case study in Padang, Indonesia

<table>
<thead>
<tr>
<th>DATA SOURCES</th>
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<tr>
<td>OSM</td>
<td>Road network (road segment length)</td>
<td>Provided through an open license.</td>
</tr>
<tr>
<td><strong>CRASHES</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Waze</td>
<td>Road alerts (crashes reported by users, coordinates)</td>
<td>Obtained through DDP.</td>
</tr>
<tr>
<td><strong>ROAD CHARACTERISTICS</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mapillary (images and tags)</td>
<td>Street view image detections (crosswalk, curb, guard rail, human, marking, pothole, sidewalk, sign, streetlight, traffic sign, utility pole)</td>
<td>Selection of image annotation tags in study; more available through Mapillary Traffic Sign and Vistas. Multiple detections per image are possible.</td>
</tr>
</tbody>
</table>

Padang Results

In Padang, preliminary results pointed to the framework’s potential in scanning roads for safety. Figure 18 shows predictions where arterial road segments were predominately designated as high risk (red lines). Residential areas were interspersed with low- and high-risk road segments. Similar patterns of road segments predicted as high risk along arterial roads and a mix of low and high risk along residential and tertiary road segments were largely found.
In general, where there were crashes reported by Waze, high-risk road segments were predicted. These preliminary results were encouraging; however, verifying the results was difficult because there was not sufficient data. While the deployment of the framework in Padang requires further validation with more data, ML-based approaches such as this are promising to offer initial road safety scans.

3.5 Findings

The Integrated Framework for Road Risk Prediction demonstrates the strength of ML to identify road segment safety with substantial accuracy (72.5 percent) in Bogotá. Preliminary results in Padang support replicating the framework with further validation in other areas. Using advanced ML techniques, the framework applied a streamlined approach that relied on road characteristics and crash frequency to determine crash risk in the training phase. Then the ML models applied in the deployment phase could predict road risk based on road characteristics without historical crash data.

The alternative data sources used to train the models were robust – thousands of annotations, high-resolution images, and crash data joined to extensive road networks – and of suitable quality for the models to provide a road safety scan. To identify road characteristics, the RIC was trained using the Mapillary Vistas Dataset, which has a breadth and depth of annotations from different contexts, providing geographic diversity. The RRE was trained using a pairing of the road characteristics and a road network database created from OSM road segments and Waze crash data. OSM road segments
offered global scalability and were sufficient for a coarse assessment in these case studies. Waze data availability was dependent on the area (and the users of the app). Given the potential for duplicate crash reports, Waze data was not relied on for accurate crash data in Bogotá; instead, it was used to identify crash patterns of high- and low-risk road segments.

The framework is not suitable for detailed road assessments. However, it can be applied to screen roads for safety without historical crash data if the RIC model is enhanced with more training data and calibrated for the local street view context; the RRE model can be modified and enhanced with fine-grained training data. It is replicable in other areas with the following recommendations, which are applicable for developing other ML-based frameworks for road safety.

Incorporate training data to fine-tune the model for a specific location. Typically, ML models trained on data collected from one region do not work well for a new region. This is called domain shift: the testing data has a different distribution than the training data. In this case, including data collected from the new region in the training phase will usually help. It is important to evaluate the data and consider any influences the collection method may have on the potential to introduce bias into the project. For example, if local crash data is introduced to train the RRE, it would help validate and potentially improve the model's application in the location of interest. Both RIC and RRE can be continually trained with newly obtained data so that the knowledge learned from previous data can be carried on for new regions while the model is still applicable to the previous regions.

It is essential to ensure that models are based on sufficient, high-quality training data. In general, at least a few thousand annotations are recommended to identify objects from images with simple context, depending on the characteristics of the object. Whether the street view images are obtained through big data platforms such as Mapillary or collected by the team, street view imagery covering different geographical regions makes the trained object detection model, like the RIC, more robust. Since street level images capture the visual scene (road characteristics and road users) at a single point in time, it is important to consider these implications when using a snapshot of that time of day, day of week, and season. Relationally, a road characteristic may be covered or occluded in a street view image; for instance, when a passing truck blocks a sign. Imagery collected at a frequent distance, such as every two meters, permits greater flexibility to analyze the road scene and predict risk using the RIC and RRE. OSM road networks require review for recency and accuracy, and possibly editing to ensure suitable quality and coverage in other areas. If high-quality, granular crash data shows a clear pattern of more risk classes, three classes could be predicted: for example, high, medium, and low risk.
Conclusion

Big data and ML offer promising opportunities to improve current road safety assessment procedures for sustainable development. Road safety assessments are often required for new transport and infrastructure developments to be approved or as part of their monitoring and evaluation once they are completed. However, conducting road safety assessment procedures can be expensive and time-consuming. Alternative data sources and ML can optimize this process by identifying patterns using complex predictive models. The Integrated Framework for Road Safety offers one approach using street view imagery that can be accessed through Mapillary or collected by the team to provide a road safety scan. With further training, this framework has the potential to provide detailed road safety assessments, mitigating the need for manual annotations (or years of historical crash data). In addition to the pilots and studies conducted by the researchers and representatives of road safety organizations interviewed for this note, there are many ML models contributing to road safety efforts, which typically outperform statistical models in predicting road safety.\(^{55}\)

Integrate alternative data sources and ML into road safety assessments with care. Finding valid, representative data can be a significant challenge in evaluating risks and reducing crash fatalities and injuries through data-driven, evidence-based interventions. Teams can directly partner with private companies and data providers to retrieve alternative sources of data. And data sharing platforms, such as DDP, offer streamlined solutions. However, commercial data sources are not typically established to collect data for road safety analysis, and their data may be inadequate for road safety assessment methods and procedures. Data can be biased, incomplete, and challenging to synchronize with conventional analytical tools. The implications of collecting and analyzing big data using ML require thorough consideration. Data privacy and security are central concerns; data needs to be de-identified and anonymized and stored according to institutional guidelines.\(^{56}\) Data and models need to be screened for biases that can affect their outcomes. For example, imbalanced access to smartphones or social media may amplify gender or community bias.\(^{57}\) Teams can adhere to best practices and data policies and make their ML models and results transparent and openly shared. Resources such as “A Framework for Understanding Sources of Harm throughout the Machine Learning Life Cycle” and “The Ethics of Artificial Intelligence” may be helpful for teams implementing ML in their projects.\(^{58}\)

The approach used for the case studies in this note can be extended to evaluate specific measures of road safety. For example, while the framework uses the crash frequency and may identify the number of relevant road users in a street view image, it does not thoroughly consider the number of (vulnerable) road users nor does it consider the probability of a crash causing fatalities or serious in-

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juries. The approach could also be extended using complementary data such as road geometry, traffic flow, traffic volume, traffic speed, weather, season, and other factors affecting visibility along the road or road surface conditions. The case studies illustrate the potential of big data and ML to reduce the manual inspection of roadways and provide road safety insight where otherwise the information is in short supply, thereby contributing to safer roads.

For big data to be fully leveraged for road safety analysis, governments, road safety advocates, and international development organizations will want to consider investing in platforms and tools that specialize in collecting and analyzing data for road safety. Ongoing efforts to establish regional road safety data observatories provide an opportunity to gather data providers and create a data marketplace specifically for road safety analysis, especially where alternative or traditional sources are scarce. Government regulations and initiatives to encourage private companies to share data could further integrate big data in international development projects, including road safety. It is essential for key stakeholders in road safety assessment to collaborate closely with pioneers of these technologies to realize their potential in road safety analysis.\(^{59}\) Initiatives such as the Artificial Intelligence in Road Traffic Crash Prevention Roundtable hosted by the International Transport Forum (ITF) in early 2021 is an example of one such opportunity. Conversations with World Bank team leaders and transport specialists reveal that developing a tool to provide a single, easy-to-use solution to access and utilize big data for road safety analysis is in high demand. There is potential to automate some of the processing and analysis for which specialist expertise is currently required, and initiatives such as Ai-RAP and the World Bank Simplified Methodology suggest that practical, scalable solutions could be a reality soon.\(^{60}\) As big data and ML become more accessible, and as their adoption accelerates worldwide, road safety practitioners, governments, road safety advocates, and international organizations can unlock their immense potential to improve the quality and efficiency of road safety assessments.


\(^{60}\) Monica Olyslagers (Safe Cities and Innovation Specialist, iRAP) and Satoshi Ogita (Senior Transport Specialist, World Bank), in discussion with the authors, April 2021.
## ANNEX 1:
**Most Relevant Big Data Types for Road Safety Analysis**

<table>
<thead>
<tr>
<th>DATA COLLECTION</th>
<th>POTENTIAL SOURCES</th>
<th>POTENTIAL APPLICATIONS</th>
<th>ADVANTAGES</th>
<th>LIMITATIONS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Street view imagery</td>
<td>• Apple Look Around</td>
<td>Identify road attributes for road safety assessments.</td>
<td>• Provides objective evidence of conditions in the field.</td>
<td>• Coverage is incomplete, particularly in rural and low-income areas.</td>
</tr>
<tr>
<td></td>
<td>• Google Street View</td>
<td></td>
<td>• Can be used in regions where government data is not available.</td>
<td>• Licensing restrictions for ML application.</td>
</tr>
<tr>
<td></td>
<td>• KartaView</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Mapillary</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Collected by team</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mobile applications and</td>
<td>• Mobile application data</td>
<td>Identify vehicle movement, traffic flows and road use by various types of users for crash risk, identification and road safety assessments.</td>
<td>• App data is usually low cost and current.</td>
<td>• Coverage is lighter in rural areas or cities where use of app is low.</td>
</tr>
<tr>
<td>telematics</td>
<td>• Telematic companies</td>
<td></td>
<td>• Telematic data could show risky driving behavior.</td>
<td>• Often requires data sharing agreements with private companies.</td>
</tr>
<tr>
<td></td>
<td>• Rideshare companies</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Crowdsourced</td>
<td>• Waze</td>
<td>Obtain crash data and information related to road use, such as types of road users and their relative density at a specific location. Can help to identify road risks.</td>
<td>• Can supplement government data, particularly if incidents are underreported or government provided road networks are unavailable.</td>
<td>• Requires app use in the region of interest.</td>
</tr>
<tr>
<td></td>
<td>• Delivery drivers</td>
<td></td>
<td></td>
<td>• Needs coordination and resources to collect reports from delivery drivers.</td>
</tr>
<tr>
<td></td>
<td>• OSM</td>
<td></td>
<td></td>
<td>• Data quality may be low.</td>
</tr>
<tr>
<td></td>
<td>• Social media</td>
<td></td>
<td></td>
<td>• Social desirability bias can occur, where users feel inclined to share specific types of information to reinforce a positive or negative perspective.</td>
</tr>
<tr>
<td>Government</td>
<td>• Government transport agencies</td>
<td>Most frequently used to obtain crash data, including statistics related to crash severity, crash frequency as well as fatalities and injuries statistics.</td>
<td>• Data often has many attributes or details that have been manually added.</td>
<td>• Data can be messy (human error).</td>
</tr>
<tr>
<td></td>
<td>• Road safety observatories</td>
<td></td>
<td>• Data often has been collected for many years in the same manner, allowing for temporal analysis.</td>
<td>• Data often not shared.</td>
</tr>
<tr>
<td>Aerial and satellite</td>
<td>• Earth observation agencies</td>
<td>Identify road attributes for road safety assessments.</td>
<td>• Covers large geographic area.</td>
<td>• Requires balancing the cost with recency and granularity of imagery.</td>
</tr>
<tr>
<td>imagery</td>
<td>• Private companies</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Meteorological sensors</td>
<td>• Meteorological agencies</td>
<td>Review weather conditions that may affect road safety, such as crashes.</td>
<td>• Infer driving conditions (i.e., if road surface conditions are not available in government crash data).</td>
<td>• There are varying levels of granularity.</td>
</tr>
<tr>
<td></td>
<td>• Local universities</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Private companies</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*SOURCE: Original table for this publication.*
# ANNEX 2: Overview of Big Data Sources

## STREET VIEW IMAGERY

<table>
<thead>
<tr>
<th>DATA</th>
<th>ACCESS</th>
<th>ATTRIBUTES</th>
<th>RESOLUTION AND FORMAT</th>
<th>COST</th>
<th>COMMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Apple Look Around</td>
<td>Early stages; contact company</td>
<td>Requires processing to derive physical features related to road safety, such as: crosswalks, speedbumps, painted lines, roads, road shoulders, sidewalks, streetlights, traffic signs and others specific to region of interest.</td>
<td>Image N/A</td>
<td>Free</td>
<td>Offers extremely limited geographic coverage.</td>
</tr>
<tr>
<td>Google Street View</td>
<td>Not accessible according to license</td>
<td></td>
<td>360 photos must be at least 4K (image)</td>
<td>N/A</td>
<td>Global coverage is fairly extensive.</td>
</tr>
<tr>
<td>KartaView</td>
<td>Open license</td>
<td></td>
<td></td>
<td>Free</td>
<td>Images are free, though image processing is required (see street view training data); global coverage is variable.</td>
</tr>
<tr>
<td>Mapillary</td>
<td>Publicly available</td>
<td></td>
<td></td>
<td>Free</td>
<td>Images are free, though image processing is required (see street view training data); global coverage is variable.</td>
</tr>
<tr>
<td>Collected by team</td>
<td>Requires permission and coordination with local government</td>
<td></td>
<td></td>
<td>High</td>
<td>Collection every two meters recommended for images. Images or video require processing; see street view training data.</td>
</tr>
</tbody>
</table>

## STREET VIEW TRAINING DATA

<table>
<thead>
<tr>
<th>DATA</th>
<th>ACCESS</th>
<th>ATTRIBUTES</th>
<th>RESOLUTION AND FORMAT</th>
<th>COST</th>
<th>COMMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mapillary Traffic Sign</td>
<td>Attribution-NonCommercial-ShareAlike 4.0 International License</td>
<td>Traffic signs</td>
<td>Resolution can be very high or very low. The model performs best on images with the same resolution level of the training dataset. (image)</td>
<td>Free</td>
<td>More than 300 traffic sign classes covering six continents.</td>
</tr>
<tr>
<td>Mapillary Vistas</td>
<td>Attribution-NonCommercial-ShareAlike 4.0 International License</td>
<td>Physical features related to road crosswalks, speedbumps, painted lines, roads, road shoulders, sidewalks, streetlights, traffic signs (others possible)</td>
<td></td>
<td>Free</td>
<td>Coverage spans six continents.</td>
</tr>
<tr>
<td>Annotation by team</td>
<td>Hire a team</td>
<td>Physical features related to road, specific to region of interest crosswalks, speedbumps, painted lines, roads, road shoulders, sidewalks, streetlights, traffic signs (others possible)</td>
<td></td>
<td>High</td>
<td>Consider collaborating with stakeholders in a region of interest to label images using a Computer Vision Annotation Tool (CVAT) or a labeling team with training. 2,000 labels per class is recommended for a simple classification.</td>
</tr>
<tr>
<td>World Bank’s GRSF Road Risk Assessment software</td>
<td>Open source</td>
<td>Physical features related to road road grade and curvature, pedestrian crossings, delineation, roadside severity, lane width, and number of lanes</td>
<td></td>
<td>Free</td>
<td>Video analysis produces a richer dataset. Piloted in Liberia and Mozambique.</td>
</tr>
</tbody>
</table>

*The software is included in this section as video training data is limited in World Bank countries. Contact Satoshi Ogita (World Bank), for access.*
<table>
<thead>
<tr>
<th>DATA</th>
<th>ACCESS</th>
<th>ATTRIBUTES</th>
<th>RESOLUTION AND FORMAT</th>
<th>COST</th>
<th>COMMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>MOBILE APPLICATIONS AND TELMATIC</strong>S</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Grab</td>
<td>Contact company</td>
<td>Contact company</td>
<td>N/A</td>
<td>N/A</td>
<td>Coverage offered in Cambodia, Indonesia, Malaysia, Myanmar, Philippines, Singapore, Thailand, Vietnam.</td>
</tr>
<tr>
<td>HERE</td>
<td>Not accessible</td>
<td>Traffic</td>
<td>Every minute (text, number)</td>
<td>N/A</td>
<td>Detailed road network coverage in more than 200 countries and comprehensive traffic speeds in more than 80 countries.</td>
</tr>
<tr>
<td>Mapbox Movement</td>
<td>Contact company</td>
<td>Movement</td>
<td>Aggregated daily or monthly at 100</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Mapbox Traffic</td>
<td>Contact company</td>
<td>Traffic (typical speed)</td>
<td>Typical speed per road segment in</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Moovit</td>
<td>Contact company</td>
<td>Urban transit (public and on-demand)</td>
<td>Contact company</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Ola Cabs</td>
<td>Contact company</td>
<td>Travel time and potholes</td>
<td>Contact company</td>
<td>N/A</td>
<td>Coverage provided in India.</td>
</tr>
<tr>
<td>Orbital Insight</td>
<td>Contact company</td>
<td>Foot traffic</td>
<td>Each minute; 2019 to present (text,</td>
<td>N/A</td>
<td>Foot traffic using mobile location data in region of interest, subject to data availability per country.</td>
</tr>
<tr>
<td>TomTom</td>
<td>Contact company</td>
<td>Traffic</td>
<td>Every minute per road segment (text,</td>
<td>Free to Medium</td>
<td>Global coverage is variable.</td>
</tr>
<tr>
<td>Uber Movement</td>
<td>Contact company</td>
<td>Traffic</td>
<td>Average travel time, average</td>
<td>Free</td>
<td>Limited geographic coverage to a selection of major cities. Currently no API.</td>
</tr>
<tr>
<td>Unacast</td>
<td>Contact company</td>
<td>Human movement</td>
<td>Coordinates, horizontal accuracy,</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Veraset</td>
<td>Contact company</td>
<td>Human movement</td>
<td>Coordinates, horizontal accuracy,</td>
<td>N/A</td>
<td>Veraset Movement covers 150 countries.</td>
</tr>
<tr>
<td>DATA ACCESS ATTRIBUTES</td>
<td>COST</td>
<td>COMMENTS</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>------------------------</td>
<td>------</td>
<td>----------</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Contact company to become a partner</strong></td>
<td><strong>Traffic (alerts, jams, irregularities)</strong> major and minor crashes; severity of congestion or irregularities; current and typical speed on jammed segments; coordinates, road segment (start and end node), street name; road type; driving direction (NSEW); turn type; alerts (construction, road closure and weather)</td>
<td><strong>Free for partners</strong></td>
<td>Includes weather alerts and major and minor crashes by application users; see Waze under Crowdsourced section.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Whereis MyTransport**
- **Contact company**
- **Informal transit network**
- **Determined in collaboration with team**
- **Medium to High**
- Specializes in producing informal transit data according to General Transit Feed Specifications (GTFS). Supports team in collecting and processing data in exchange for the team covering in-field costs of data collection and facilitating engagement with local transport authorities.

**Crowdsourced**

**OSM**
- **Open license**
- **Road segments (road type, length) and road features**
- **Centerline of road segments, referred to as ways and relations (text, number)**
- **Free**
- May include additional road attributes: lanes, name, smoothness, surface, speed limit, and width, and other information such as overtaking permitted or lighting.

**Twitter**
- **API**
- **Road incidents tweeted**
- **User-dependent; can be associated with a place or location (text, number)**
- **Free to medium**
- Price dependent on account type and data volume.

**Waze**
- **Contact company to become a partner**
- **Road incidents reported using app**
- **Every minute; location provided as coordinates, road segment, street name (text, number)**
- **Free for partners**

**Delivery drivers**
- **Coordinated by team**
- **Road incidents reported using app**
- **Depends on collection (text, number)**
- **High**

**Government or road safety observatory**
- **Government contact or open data platform**
- **Incidents (date, time, severity, type)**
- **XY coordinate per incident (text, number)**
- **Free to Low**
- Processing requires standard GIS software such as ArcGIS (paid) or QGIS (free).

- **Road segments (type, width, speed limit)**
  - **Low**
- **Traffic lights (intersection type)**
  - **XY coordinate per traffic light (text, number)**
  - **Low**
  - May include intersection type (pedestrian, bicyclist, for example)
<table>
<thead>
<tr>
<th>DATA ACCESS ATTRIBUTES</th>
<th>RESOLUTION AND FORMAT</th>
<th>COST</th>
<th>COMMENTS</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>REMOTE SENSING</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Maxar Technologies</td>
<td>Contact company</td>
<td>Elevation and roads</td>
<td>Less than 1m (image)</td>
</tr>
<tr>
<td>Orbital Insight</td>
<td>Contact company</td>
<td>Car and truck count; roads</td>
<td>Car and truck count: high resolution, 2013 to present; roads: medium resolution, 2016 to present (image, number)</td>
</tr>
<tr>
<td>Security or traffic cameras</td>
<td>Collected by team or through external resource</td>
<td>Traffic density and volume</td>
<td>Depends on camera (image or video)</td>
</tr>
<tr>
<td>Unmanned aerial vehicle (UAV)</td>
<td>Collected by team</td>
<td>Elevation, roads, traffic density and volume</td>
<td>Depends on camera (image or video)</td>
</tr>
<tr>
<td><strong>METEOROLOGICAL SENSORS</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>OpenWeather</td>
<td>Contact company</td>
<td>Weather (weather type, temperature, wind speed and direction, cloud coverage; rain and snow volume by hour and per 3 hours)</td>
<td>40-year historical archive for any coordinates by the hour; or by city or 1 km, 5 km, 10 km or customized grid (text, number)</td>
</tr>
<tr>
<td>Tomorrow.io</td>
<td>Contact company</td>
<td>Weather (weather type, temperature and humidity; wind speed, direction, gust; precipitation type, intensity; snow and ice accumulation; visibility, moon phase)</td>
<td>500m radius with precipitation recordings as low as 30 feet off the ground; time steps range from one day to one minute (text, number)</td>
</tr>
</tbody>
</table>

SOURCE: Original table for this publication.
ANNEX 3: Hotspots and Heatmaps: Uncovering Data Patterns for Road Safety

Data visualizations are provided in the case study regions using alternative data sources, such as OSM, Mapbox, and Waze, as well as a select government dataset.

Bogotá, Colombia

Temporal data visualizations show road safety patterns between years, seasons, months, weeks, days, and times of day. The Waze crash data used to train the ML model covered a period of six months, from July through December 2020. It was anticipated that the pandemic would affect the number of Waze crash reports, and potentially traffic patterns, as crashes reported by the government noticeably decreased compared to prior years (figure 3.1). The government dataset revealed fewer incidents starting in March 2020, suggesting that the number of crashes was affected by the pandemic, though it is worth noting that the speed limit was also reduced from 60km/h to 50 km/h in May 2020 (figure 3.2). With this in mind, the Waze data was used to identify road safety trends.
Hotspot analysis groups crash locations to determine statistically significant clusters of crashes. Government and Waze datasets were analyzed during the same six-month window (figure 3.3). Between the two datasets, similar hotspots were found near Avenida Boyacá and Calle 6 along the highway in the south, Avenida Norte-Quito-Sur (NQS). Overall, Waze had more hotspots than the government dataset. Some minor road incidents captured by Waze may have gone unreported to the police. This trend can be seen in minor collisions clustering further north in the city. This cluster does not appear in the government data. Instead, clusters of government-reported crashes with only damage (no injury or fatality) appear in a central band. The approach to identify hotspots can vary, including the clustering method, size, shape, and search area of neighboring hotspots.

FIGURE 3.3: Hotspot analysis of government and Waze crash data in Bogotá, July–December 2020

*Includes major and minor crashes, as well as those not categorized as either type.

SOURCE: Original figure for this publication, based on data from Datos Abiertos Secretaría Distrital de Movilidad and the Waze App. Learn more at waze.com. Basemap provided by Esri, HERE, Garmin, METI/NASA, USGS.
As with other alternative sources of data derived from mobile devices and apps, Waze crash reports are influenced by the location of the users, which affects where and when the crashes are reported. While Waze data notes major and minor incidents, the dataset will not include additional crash details typically obtained from an official source, such as type, severity, class, and reason. Even though users can validate reports (e.g., thumbs up) to provide a confidence and reliability rating and flag false reports, there is potential for duplication in Waze data. Deduplication was not conducted for this analysis because this study was interested in relative crash patterns.

Identifiable temporal patterns display when major crashes are aggregated by the day of the week and hour of the day (figure 3.4). In Bogotá, major crash reports increased between 6 and 7 p.m., having the most crashes during this window on Friday. Fewer incidents occurred on Sunday.

FIGURE 3.4: Major crashes reported on Waze in Bogotá, July–December 2020

SOURCE: Original figure for this publication, based on data provided by the Waze App. Learn more at waze.com.
Spatial and temporal analysis can be combined to identify areas for closer inspection that exhibit patterns over time. This is valuable given human movement or behavioral changes, including the effects of a pandemic, road construction, or updated speed limits, during the examined period. Emerging hotspot analysis reviews clusters of crashes that are consistent over time and ones that are intensifying or diminishing (figure 3.5). In this example, each week was analyzed. Intensifying hotspot areas were statistically significant hotspots for 90 percent of the weeks analyzed with increasing intensity of hotspots, including the final week.

FIGURE 3.5: Emerging hotspot analysis of Waze crashes in Bogotá, July–December 2020

SOURCE: Original figure for this publication, based on data provided by the Waze App. Learn more at waze.com. Basemap provided by Esri, HERE, Garmin, METI/NASA, USGS.

If interventions or investments target a specific road, more geographically detailed information is required to make decisions. Hotspot analysis applied to road segments visualizes statistically significant crash frequencies along roads, as shown in figure 3.6.

FIGURE 3.6: Hotspot analysis using Waze crash frequencies in Bogotá, July–December 2020

SOURCE: Original figure for this publication, based on data provided by OSM and the Waze App. Learn more at waze.com
Padang, Indonesia

Heatmaps visualize the density of crashes. While Waze data was sparse in Padang, some spatial patterns could be detected. A heatmap shows at least three distinct areas of high crash density that could be further examined during a site inspection (figure 3.7).

**FIGURE 3.7:** Heatmap of crashes reported using the Waze app in Padang, April 2019–July 2021

SOURCE: Original figure for this publication, based on data provided by the Waze App. Learn more at waze.com. Basemap provided by Esri, HERE, Garmin, METI/NASA, USGS.
Road safety assessments may require operating speeds of road segments. Mapbox collects this data from mobile devices and provides typical speeds per road segment in 5-minute increments. In Padang, Mapbox speeds were visualized for a Thursday from 5:00 p.m. to 6:00 p.m. (figure 3.8). Using the OSM road type to group and designate minor and major roads as a proxy for a low or high-speed limit (speed limits were sparsely noted in OSM), minor roads are visualized with thinner lines than major roads. The average speed typically slowed near intersections in pink (<25 km/h) when compared to major roads in purple (25-50 km/h). High-speed road segments exceeding 50 km/h are found heading north and south along Jalan By Pass. Identifying road segments with high speeds using Mapbox supports road safety assessments and the implementation of speed management or traffic calming measures.

FIGURE 3.8: Mapbox typical speeds in Padang on Thursday, 5:00 p.m. to 6:00 p.m.
ANNEX 4:
Classes Detected Using Mapillary Vistas Dataset in RIC Model and Input Classes for the RRE Model

All classes listed were detected using the Mapillary Vistas Dataset. Classes in bold were the input for the RRE Model.

animal--bird
animal--ground-animal
construction--barrier--ambiguous
construction--barrier--concrete-block
construction--barrier--curb
construction--barrier--fence
construction--barrier--guard-rail
construction--barrier--other-barrier
construction--barrier--road-median
construction--barrier--separator
construction--barrier--temporary
construction--barrier--wall
construction--flat--bike-lane
construction--flat--crosswalk-plain
construction--flat--curb-cut
construction--flat--driveway
construction--flat--parking
construction--flat--parking-aisle
construction--flat--pedestrian-area
construction--flat--rail-track
construction--flat--road
construction--flat--road-shoulder
construction--flat--service-lane
construction--flat--sidewalk
construction--flat--traffic-island
construction--structure--bridge
construction--structure--garage
construction--structure--tunnel
human--person--individual
human--person--person-group
human--rider--bicyclist
human--rider--motorcyclist
human--rider--other-rider
marking--continuous--dashed
marking--continuous--solid
marking--continuous--zigzag
marking--discrete--ambiguous
marking--discrete--arrow--left
marking--discrete--arrow--other
marking--discrete--arrow--right
marking--discrete--arrow--split-left-or-straight
marking--discrete--arrow--split-right-or-straight
marking--discrete--arrow--straight
marking--discrete--crosswalk-zebra
marking--discrete--give-way-row
marking--discrete--give-way-single
marking--discrete--hatched--chevron
marking--discrete--hatched--diagonal
marking--discrete--other-marking
marking--discrete--stop-line
marking--discrete--symbol--bicycle
marking--discrete--symbol--other
marking--discrete--text
marking-only--continuous--dashed
marking-only--discrete--crosswalk-zebra
marking-only--discrete--other-marking
marking-only--discrete--text
nature--mountain
nature--sand
nature--sky
nature--snow
nature--terrain
nature--vegetation
nature--water
object--banner
object--bench
object--bike-rack
object--catch-basin
object--cctv-camera
object--fire-hydrant
object--junction-box
object--mailbox
object--manhole
object--parking-meter
object--phone-booth
object--pothole
object--sign--advertisement
object--sign--ambiguous
object--sign--back
object--sign--information
object--sign--other
object--sign--store
object--street-light
object--support--pole
object--support--pole-group
object--support--traffic-sign-frame
object--support--utility-pole
object--traffic-cone
object--traffic-light--general-single
object--traffic-light--pedestrians
object--traffic-light--general-upright
object--traffic-light--general-horizontal
object--traffic-light--cyclists
object--traffic-light--other
object--traffic-sign--ambiguous
object--traffic-sign--back
object--traffic-sign--direction-back
object--traffic-sign--direction-front
object--traffic-sign--front
object--traffic-sign--information-parking
object--traffic-sign--temporary-back
object--traffic-sign--temporary-front
object--trash-can
object--vehicle--bicycle
object--vehicle--boat
object--vehicle--bus
object--vehicle--car
object--vehicle--caravan
object--vehicle--motorcycle
object--vehicle--on-rails
object--vehicle--other-vehicle
object--vehicle--trailer
object--vehicle--truck
object--vehicle--vehicle-group
object--vehicle--wheeled-slow
object--water-valve
void--car-mount
void--dynamic
void--ego-vehicle
void--ground
void--static
void--unlabeled
ANNEX 5:  
Average Precision of the Bounding Box Detection and Classification

An Average Precision (AP) score closer to 100 indicates a better performance in correctly detecting and classifying an object. AP scores equal to zero mean that no data is available.

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## Glossary of Terms

<table>
<thead>
<tr>
<th>Term</th>
<th>Description</th>
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<tbody>
<tr>
<td><strong>Big Data</strong></td>
<td>Large data sets that require significant processing power and/or complex computational techniques to reveal patterns, trends, and correlations.</td>
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<td><strong>Development Data Partnership (DDP)</strong></td>
<td>A partnership between international organizations and companies, created to facilitate the use of third-party data in research and international development.</td>
</tr>
<tr>
<td><strong>Deep Learning (DL)</strong></td>
<td>A branch of artificial intelligence that involves creating algorithms for deep artificial neural networks, inspired by the human brain, to learn complex patterns from high dimensional and large quantities of data.</td>
</tr>
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<td><strong>Fatalities and Serious Injuries (FSI)</strong></td>
<td>A metric of those killed or seriously injured in a traffic crash which is used to monitor traffic safety performance. Fatalities are defined as those who die within 30 days of the crash.</td>
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<td><strong>Intelligent Transport System (ITS)</strong></td>
<td>The collection, analysis, and transmission of transportation, vehicle, and infrastructure data that informs users with real-time updates and improves future operations and predictions.</td>
</tr>
<tr>
<td><strong>Internet of Things (IoT)</strong></td>
<td>Devices that are connected to the internet to send and/or receive data.</td>
</tr>
<tr>
<td><strong>Machine Learning (ML)</strong></td>
<td>Method to systematically derive patterns, identify trends, and make conclusions from data with minimal human intervention.</td>
</tr>
<tr>
<td><strong>Neural Network</strong></td>
<td>A set of connected algorithms typically organized in three layers: input layer, hidden layer(s), and an output layer.</td>
</tr>
<tr>
<td><strong>Road Crash</strong></td>
<td>The collision of a vehicle with another entity, such as a car, bicycle, stationary object, pedestrian, or animal, that causes injury or damage to one or more of the entities on a road or road-related area.</td>
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<tr>
<td><strong>Road Safety</strong></td>
<td>System to reduce risks to road users, preventing death or injury.</td>
</tr>
<tr>
<td><strong>Road Safety Assessments</strong></td>
<td>Systematic review of the current road or traffic scheme to identify hazardous areas.</td>
</tr>
<tr>
<td><strong>Road Safety Audit (RSA)</strong></td>
<td>Independent, systematic evaluation of the modification or addition to the road or traffic scheme to determine the crash potential and safety performance for all road users.</td>
</tr>
<tr>
<td><strong>Road Safety Impact Assessment (RSIA)</strong></td>
<td>The safety performance ranking of planned road construction or modification design schemes and their effect on the surrounding road network.</td>
</tr>
<tr>
<td><strong>Road Safety Observatory (RSO)</strong></td>
<td>A regional network of government representatives that facilitates the sharing and exchange of road safety data and expertise. The World Bank operates RSOs in Latin America (OISEVI), Africa (ARSO), and Asia-Pacific (APRSO).</td>
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<tr>
<td><strong>Safe System</strong></td>
<td>An approach to road safety that integrates principles for safer vehicles, safer roads, and safer users to eliminate death and serious injuries.</td>
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<td><strong>Supervised Learning</strong></td>
<td>A machine learning task using labeled data to train the model with input-output pairs.</td>
</tr>
<tr>
<td><strong>Unsupervised Learning</strong></td>
<td>A machine learning technique that extracts patterns from unlabeled data. For example, grouping or clustering data with similar attributes.</td>
</tr>
<tr>
<td><strong>Vulnerable Road Users</strong></td>
<td>Individuals at a higher risk using the road because they do not have the protection of an enclosed vehicle, such as pedestrians, motorcyclists, bicyclists, and those on animals or animal drawn carts.</td>
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</tbody>
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References


This guidance note offers a practical introduction to integrating big data and machine learning in road safety evaluations. It outlines data requirements for several road safety assessments, provides a convenient overview of relevant big data sources, and explains machine learning fundamentals for the application of these advanced technologies, specifically for road safety. The note proposes an Integrated Framework for Road Safety, which takes the reader step-by-step through a machine learning workflow to evaluate road risk, using case studies in Bogotá, Colombia and Padang, Indonesia.

The Integrated Framework for Road Safety uses machine learning to identify road characteristics from street view images and predict road segment risk based on those identifiable characteristics. As a result, road segment risk was predicted with 72.5 percent accuracy in Bogotá. While the preliminary results in Padang were encouraging, additional data is required to verify the performance in a new context. However, the workflow illustrated through these case studies shows potential for replicability. All code for the Integrated Framework for Road Safety is free and publicly available for repurposing and refining to local context through a link provided in the note.

The framework exemplifies current capabilities to reduce the reliance on manual image annotations and highlights the potential to conduct a road safety scan without years of historical crash data. The increasing availability of big data and the growing use of machine learning models for road safety point to rapidly evolving technological solutions that have immense capacity to improve the quality and efficiency of road safety assessments in developing countries.